



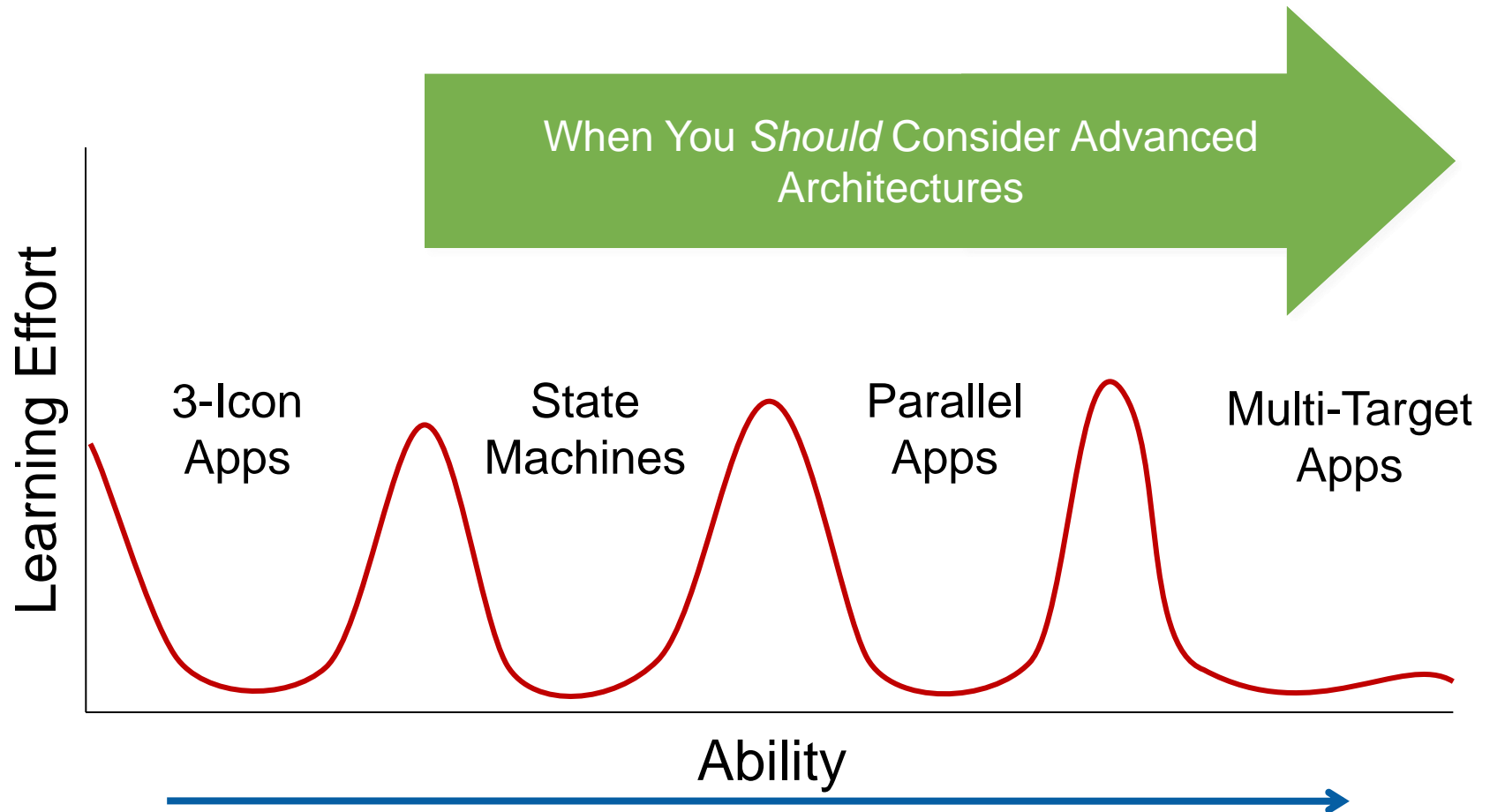
# Foundational Design Patterns for Moving Beyond One Loop

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# Agenda

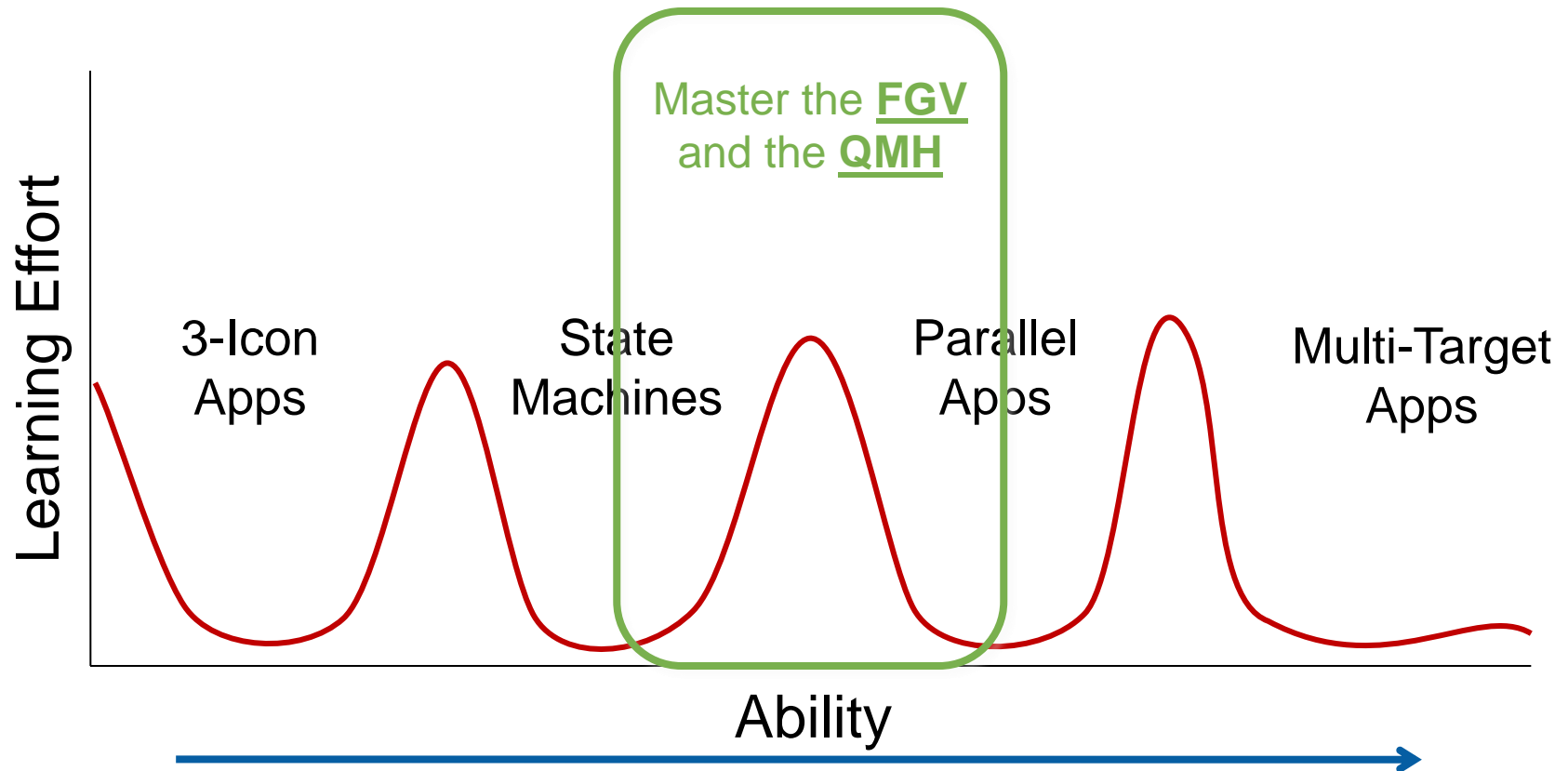
- Why move beyond one loop?
- What is a design pattern?
- Why learn communication mechanisms?
  - Functional global variables
  - Queued message handlers

# Defining Advanced Applications & LabVIEW Ability

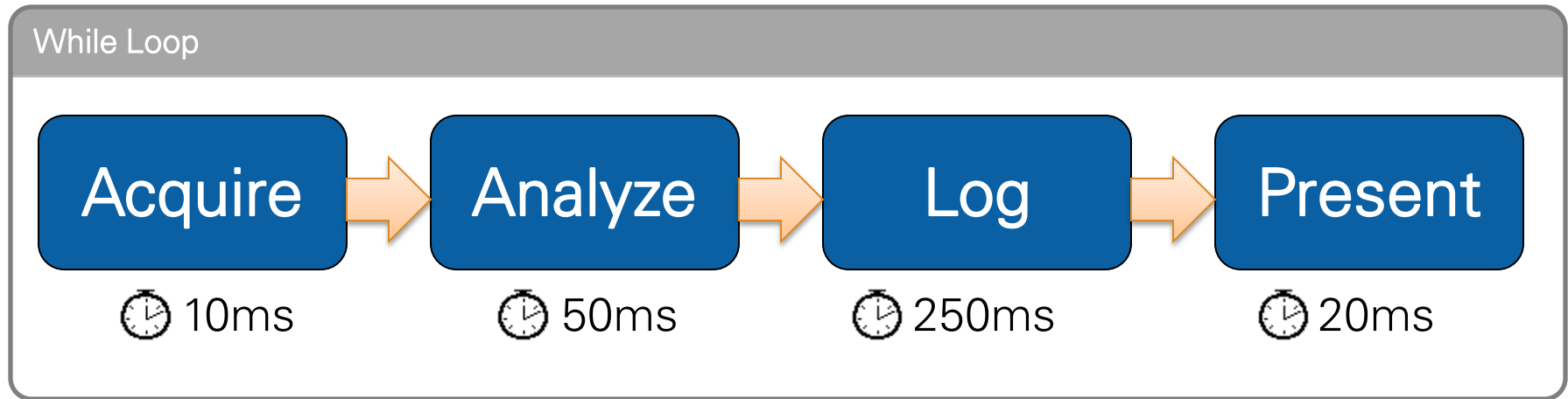


# Master Key Design Patterns...

## ...and Understand Their Limitations

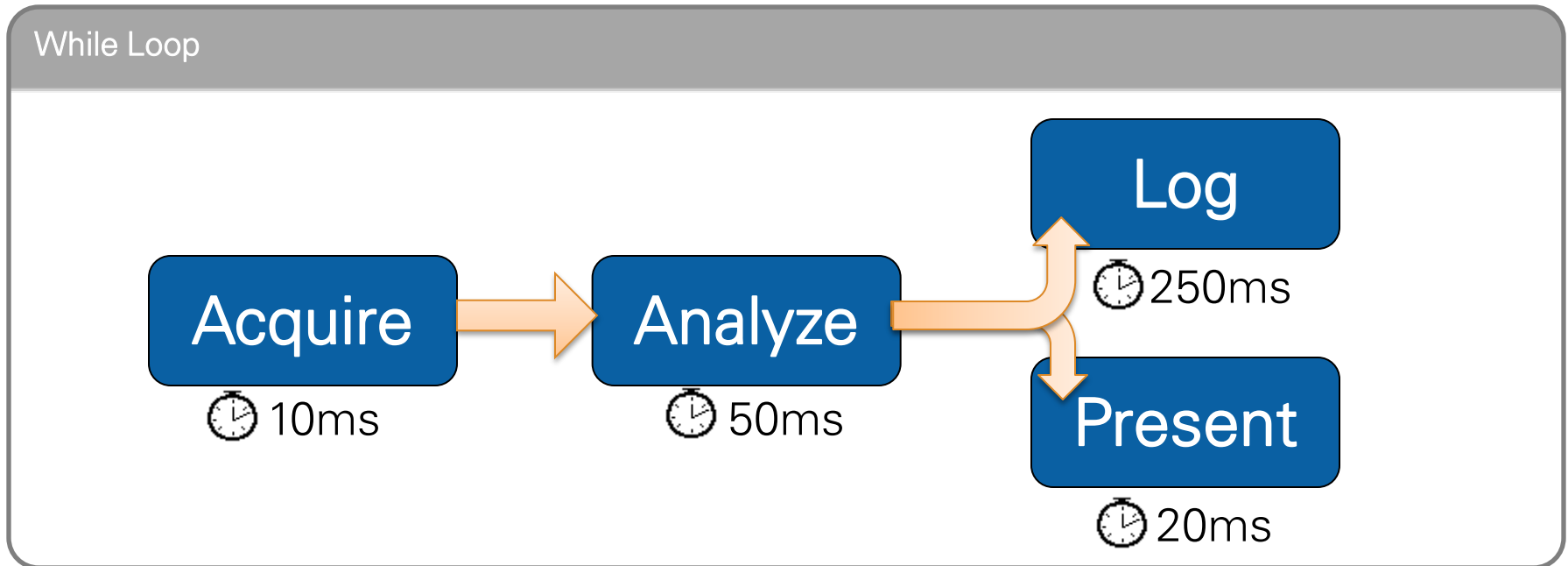


# Doing Everything in One Loop Can Cause Problems



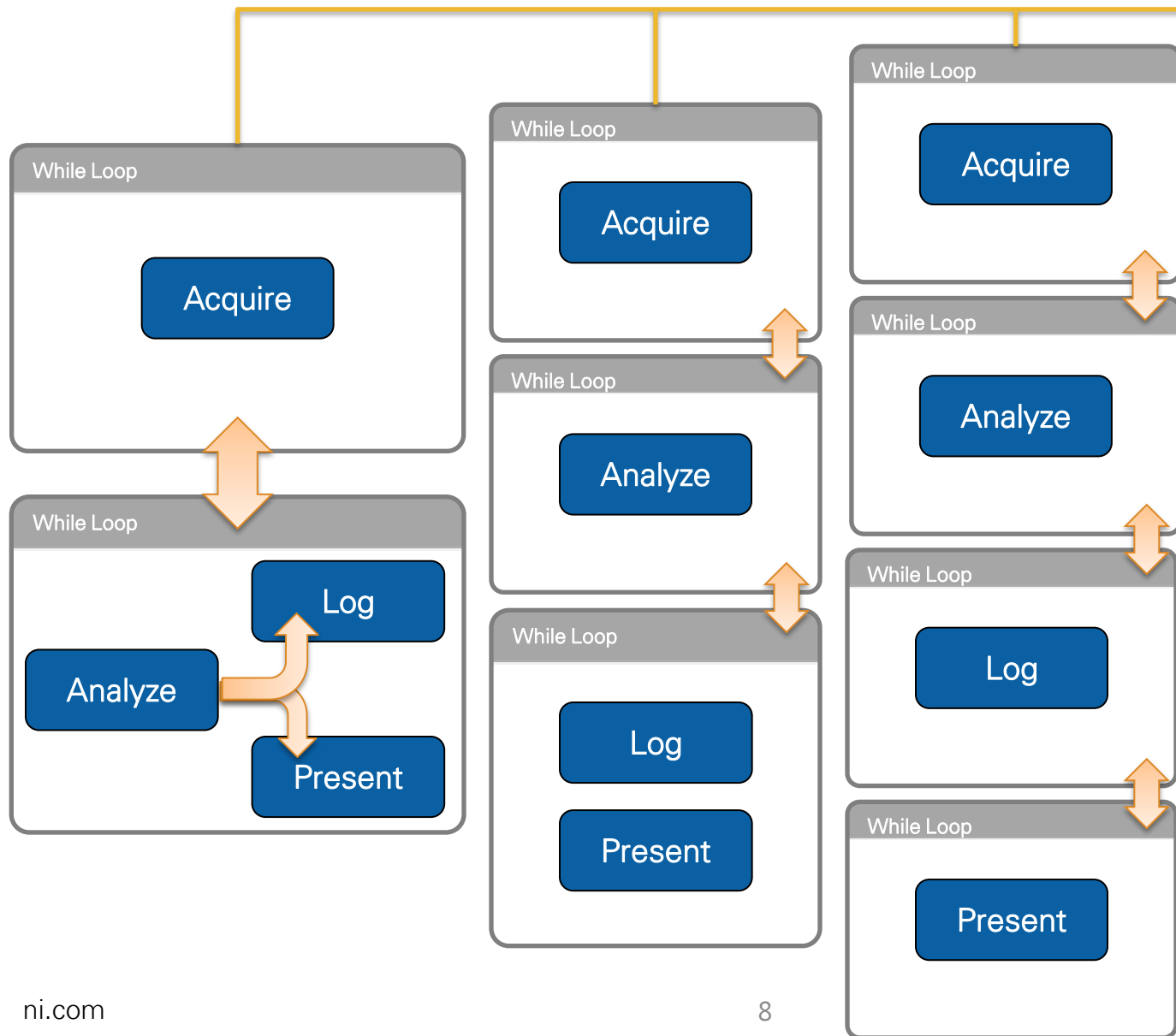
- One cycle takes at least 330 ms
- If the acquisition reads from a buffer, it may fill up
- User interface can only be updated every 330 ms

# Doing Everything in One Loop Can Cause Problems

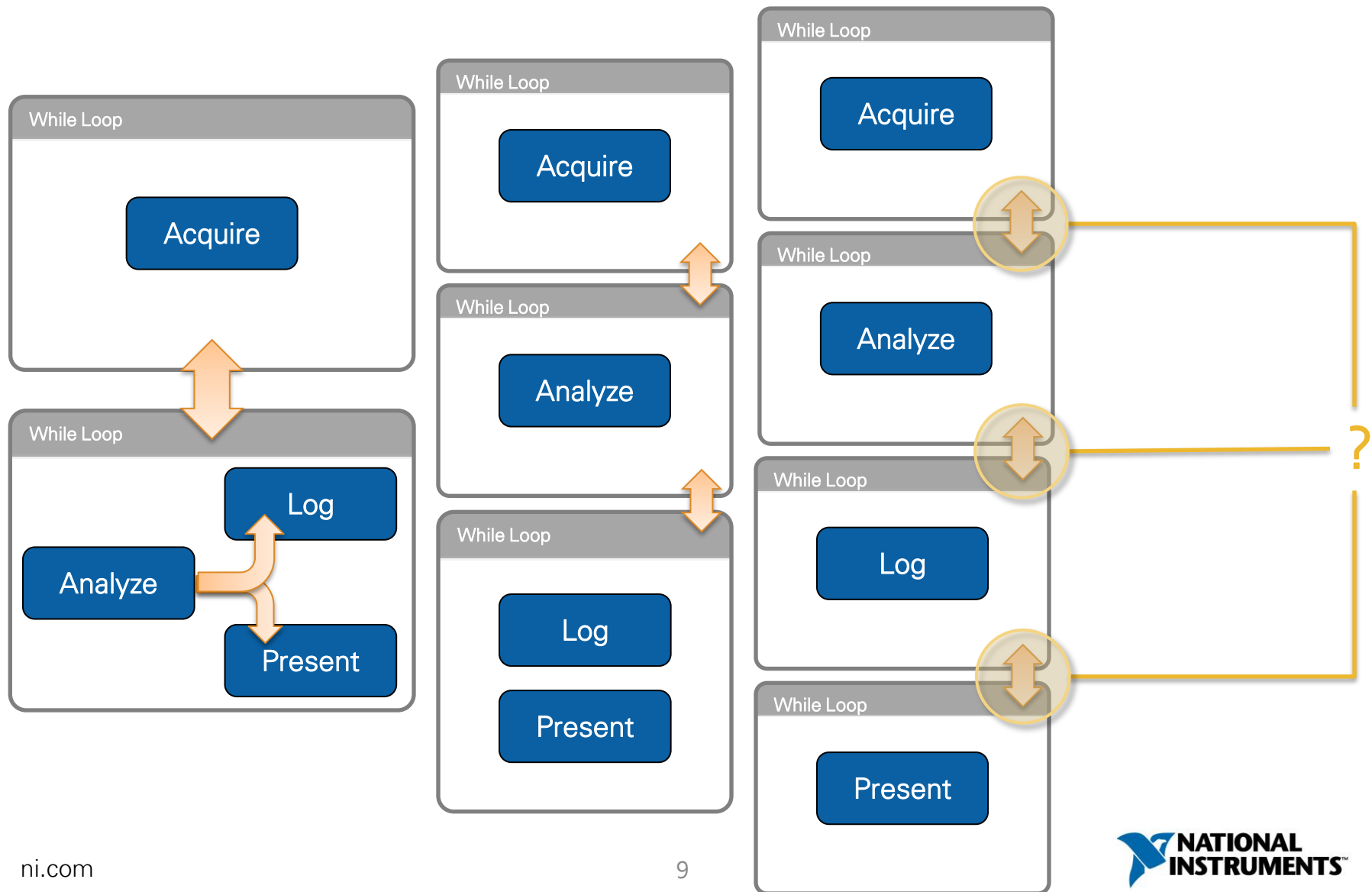


- One cycle still takes at least 310 ms
- If the acquisition reads from a buffer, it may fill up
- User interface can only be updated every 310 ms

# How do we implement multiple loops?



# How do we communicate between loops?



“Don’t Re-invent  
the Wheel...”



...or Worse,  
a Flat Tire.”

*-Head First Design Patterns*

# What is a design pattern and why use one?

- Definition:
  - A general reusable approach to a commonly occurring problem
  - Well-established, proven techniques
  - A formalized best practice
  - **Not** a finished design
- Design patterns:
  - Save time
  - Improve code longevity
  - Improve code readability
  - Simplify code maintenance

# What is the difference between a design pattern and a framework?

## Design Pattern

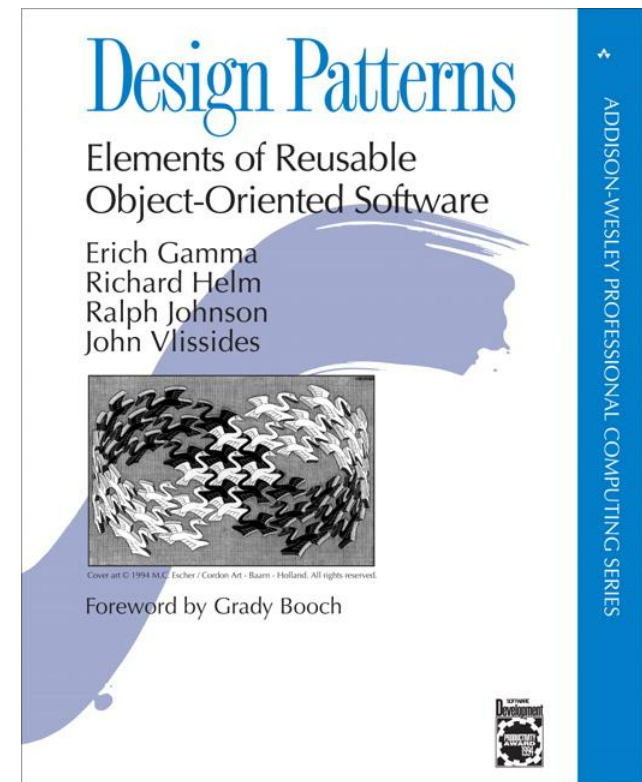
- Focuses on a specific problem
- Geared toward solo developers
- More foundational

## Framework

- Focuses on larger applications
- Geared toward team development
- Often involve an architect

# Design Patterns are **not** Specific to LabVIEW

- Gained popularity from the “Gang of Four” (GoF or Go4)
- Includes examples in C++, Smalltalk
- The LabVIEW community has adopted and extended several design patterns for use with LabVIEW
  - Examples:
    - Producer / Consumer
    - State Machine
    - Queued Message Handler
    - Factory Pattern
    - Singleton Pattern

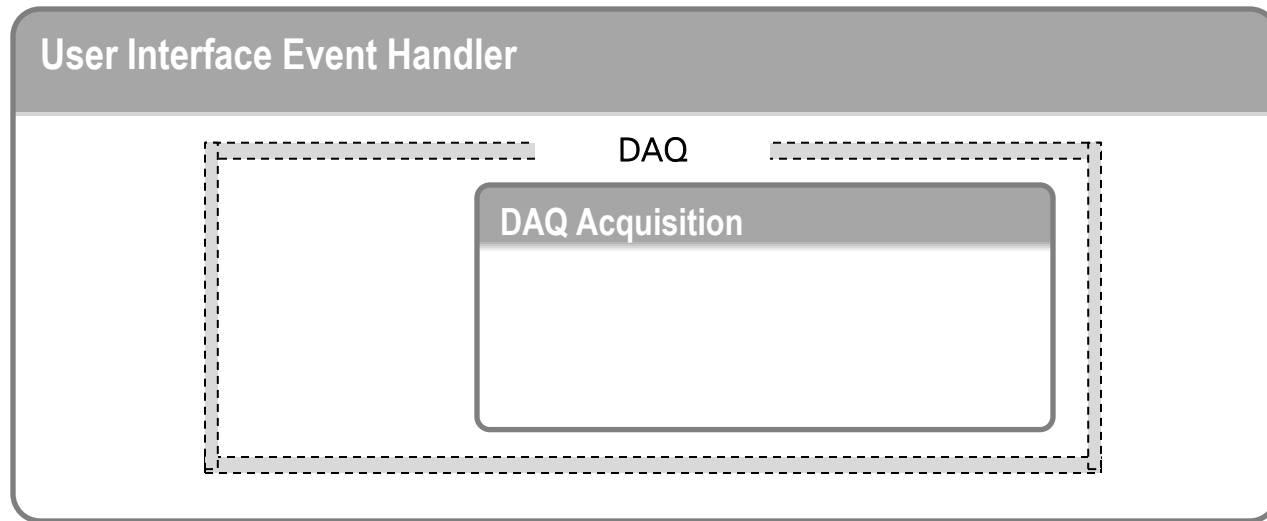


# Risks Associated with a “Flat Tire”

*(Poor Application Design)*

- Nothing happens when you press “Stop”
- Poor error handling
- No consistent style
- Complicated maintenance and debugging
- Difficulty scaling application
- Tight coupling, poor cohesion

# Why is Coupling Bad?



**Execution:** The user interface cannot respond to other input while acquiring data

**Development:** Modifying one process requires modifying the other

**Extensibility:** How do you add a data logging process?

**Fragility:** Can you fix a bug in one process without affecting another?

**Maintenance:** Can you test one piece of an application without testing its entirety?

# Coupling is Often Accidental: Case Study

*NIWeek 2011 Hummer Demo*

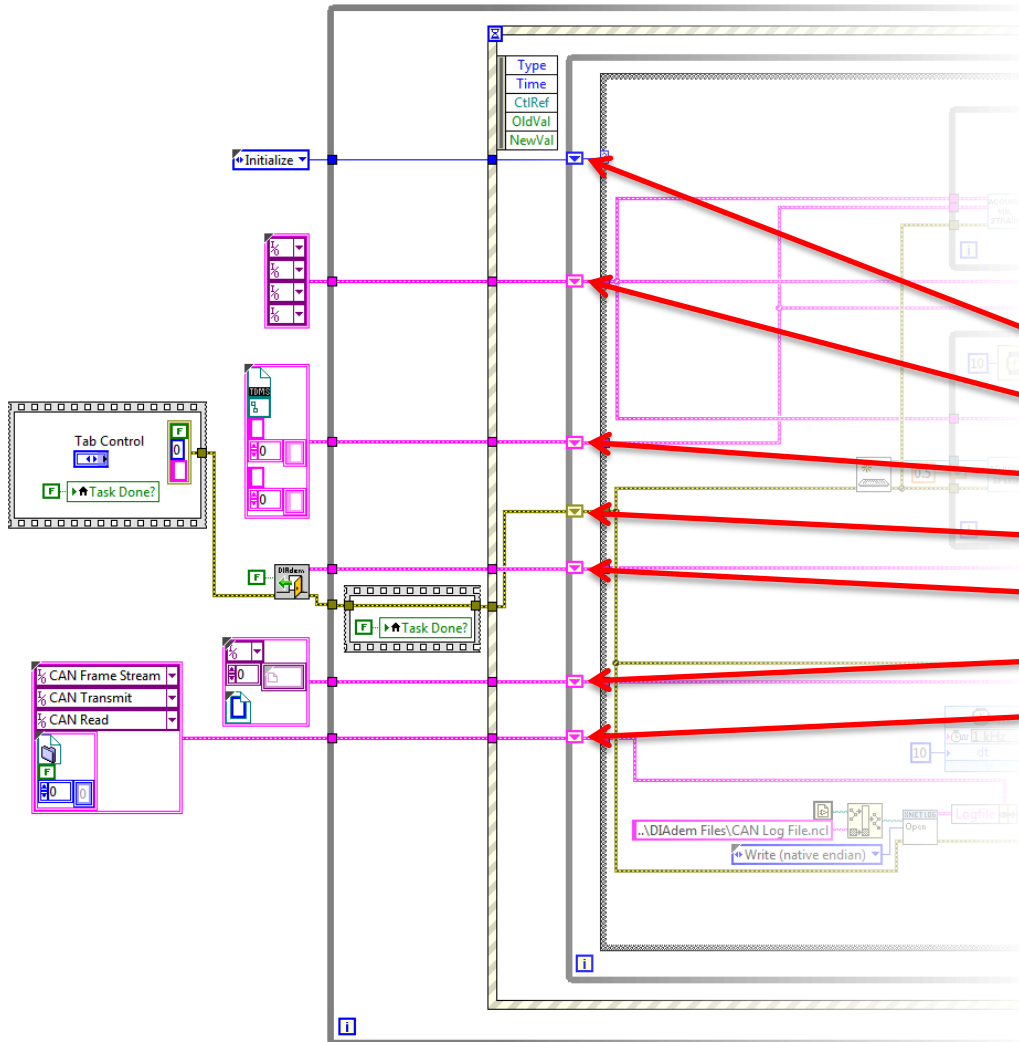
## Initial Scope

- Demonstrate:
  - Data Acquisition
  - CAN Synchronization
- Selected Architecture:
  - State Machine



# Coupling is Often Accidental: Case Study

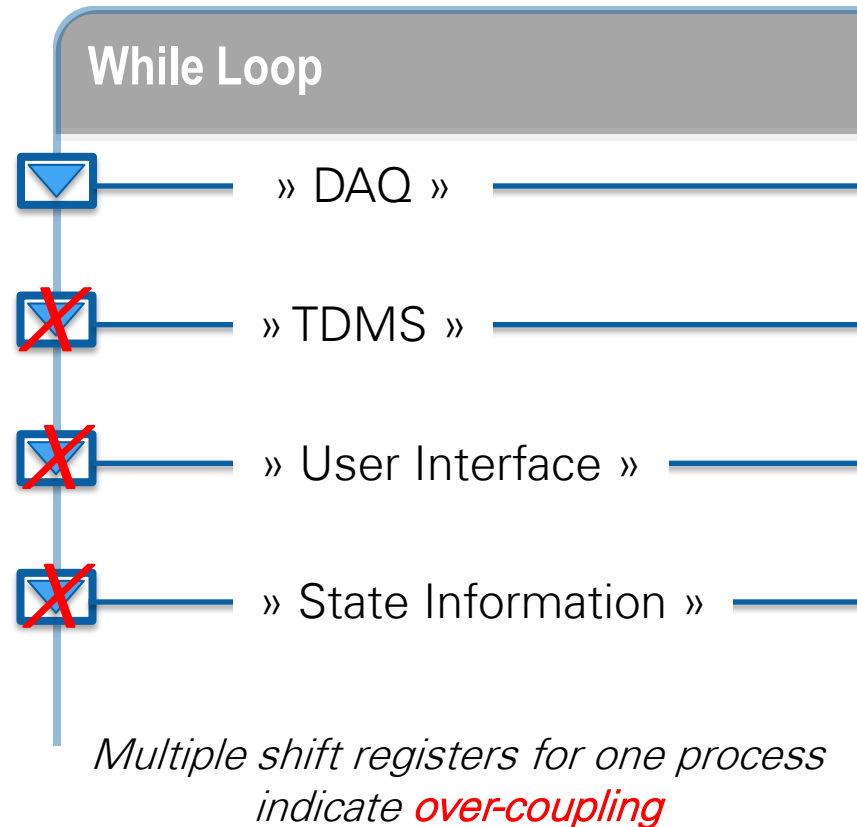
## Final Demo Code



- Once you start...you can't stop
- You can't test independent actions
- There are 7 shift registers:
  - State
  - DAQ Settings
  - TDMS Settings
  - Errors
  - DIAdem References
  - IMAQ Settings
  - CAN Settings
- Whether used or not, every shift register goes across every case

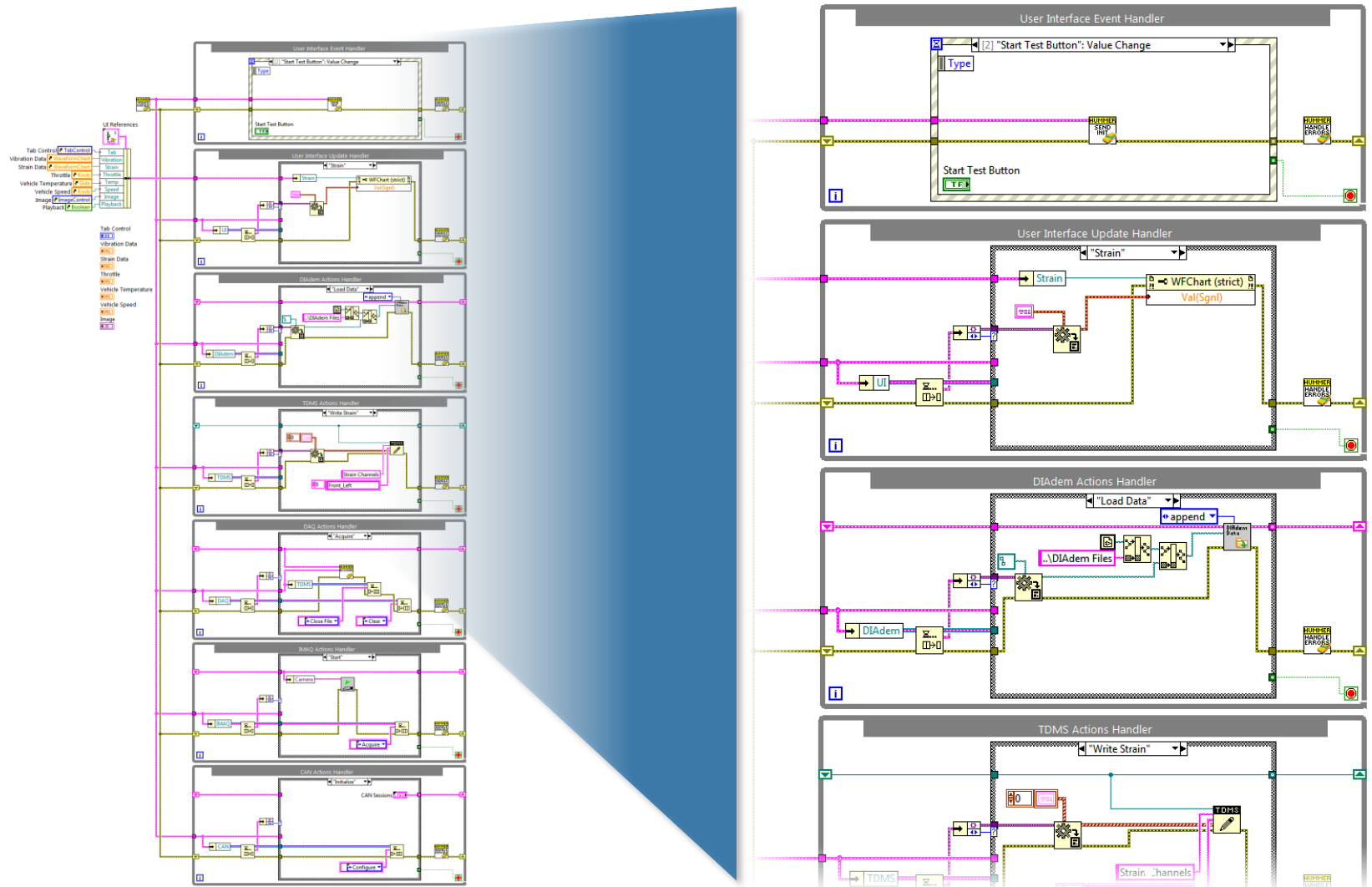
# Cohesion: Limiting Process Scope

- Often, shift register defines scope of process
- Processes should be very cohesive
- Independent processes should be separate loops
- Good example: A drop-in Functional Global Variable (FGV)



# The Rewritten Hummer Demo

*Using a Queued Message Handler Architecture*



# How to De-Couple Independent Processes

## Best Practices

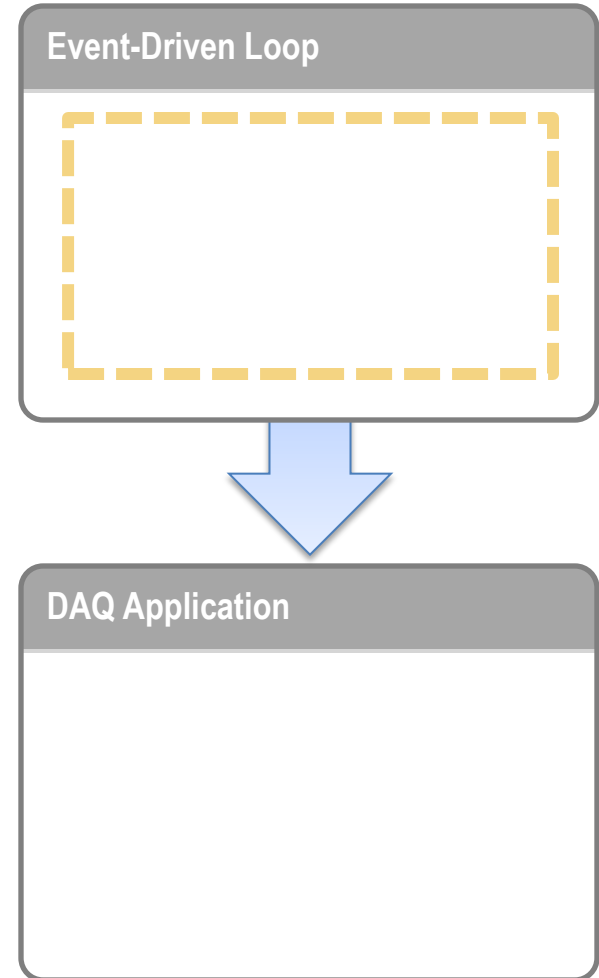
1. Identify data scope
2. Delegate actions to appropriate process
3. Avoid polling or using timeouts\*

*\*except for code that communicates with hardware*

## Considerations

1. How do you send commands?
2. How do you send data?
3. Which processes can communicate with each other?
4. How do you update the UI?

?



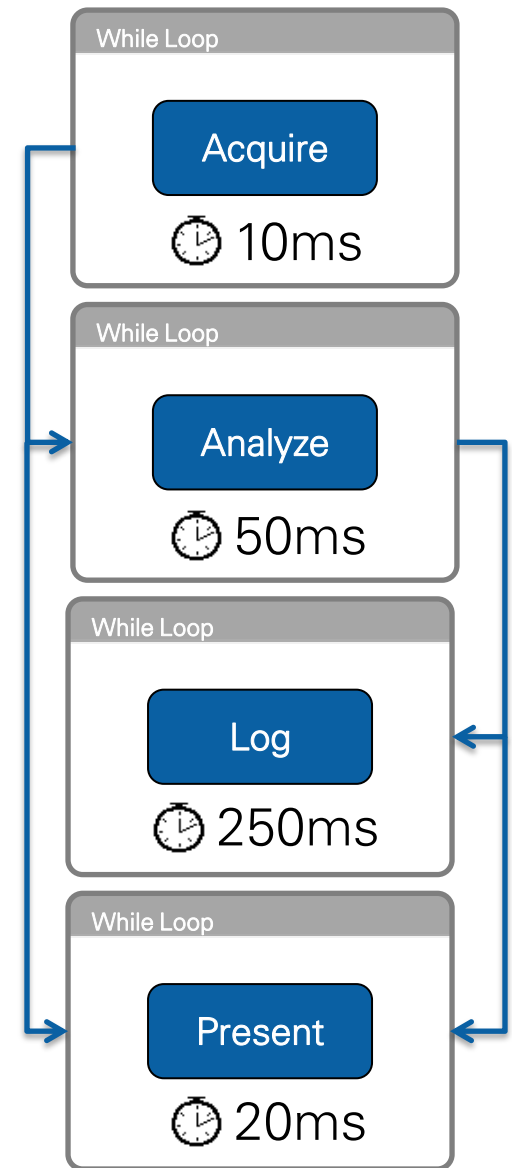
# Inter-Process Communication

ensures tasks run asynchronously and efficiently

## Goals

- Loops are running independently
- User interface can be updated every 20 ms
- Acquisition runs every 10ms, helping to not overflow the buffer
- All while loops run entirely parallel with each other

## ...How?



# Many Data Communication Options Exist in LabVIEW

*In no particular order...*

1. TCP and UDP
2. Network Streams
3. Shared Variables
4. DMAs
5. Web Services
6. Peer-to-Peer Streaming
7. Queues
8. Dynamic Events
9. Functional Global Variables
10. RT FIFOs
11. Datasocket
12. Local Variables
13. Programmatic Front Panel Interface
14. Target-scoped FIFOs
15. Notifiers
16. Simple TCP/IP Messaging
17. AMC
18. HTTP
19. FTP
20. Global variables

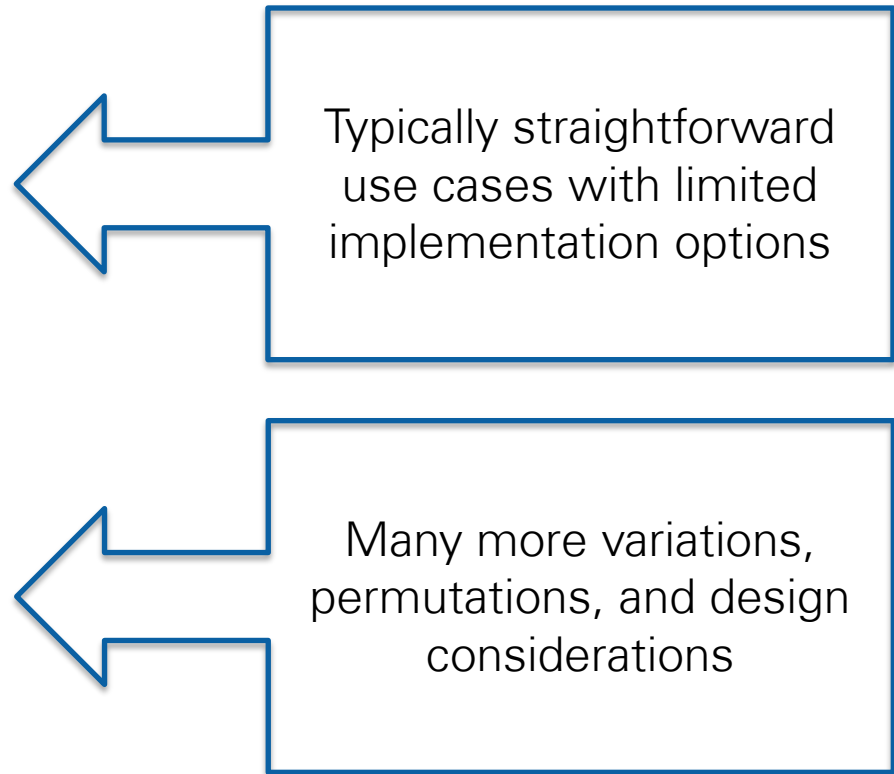
... just to name a few!

# Tactic 1: Functional Global Variables

- What is a functional global variable (FGV)?
  - Does the FGV prevent race conditions?
- Is the FGV better than the global variable?

# Inter-Process Communication

- Store Data
- Stream Data
- Send Message



# De-Facto Communication Choice: Locals / Globals

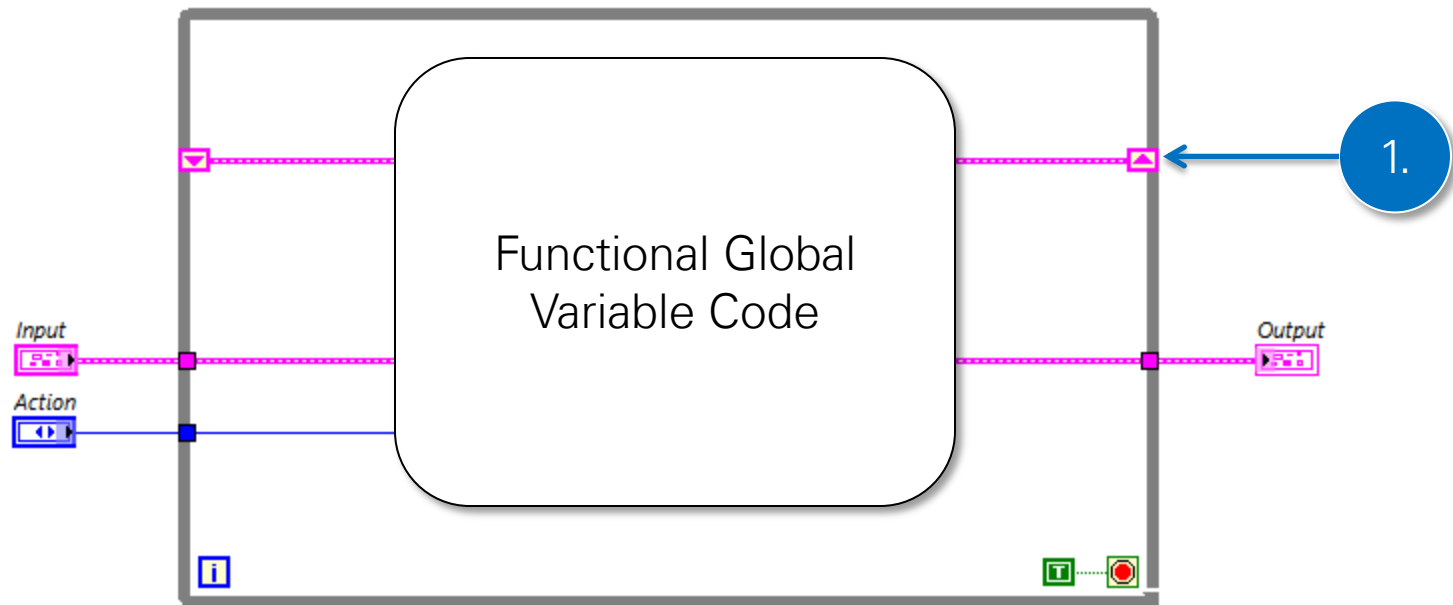
*"The traditional, text-based programmer's first instinct is always to use local variables."*

*– Brian Powell*

- Local and Global variables are simple and obvious
- Problem: Locals / Globals are **pure data storage**
- Text-based mindset isn't used to parallel programs, multithreading

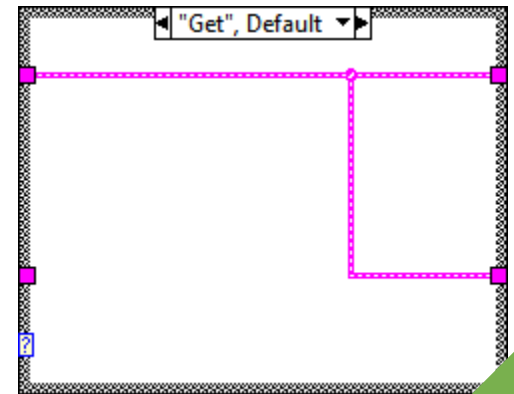
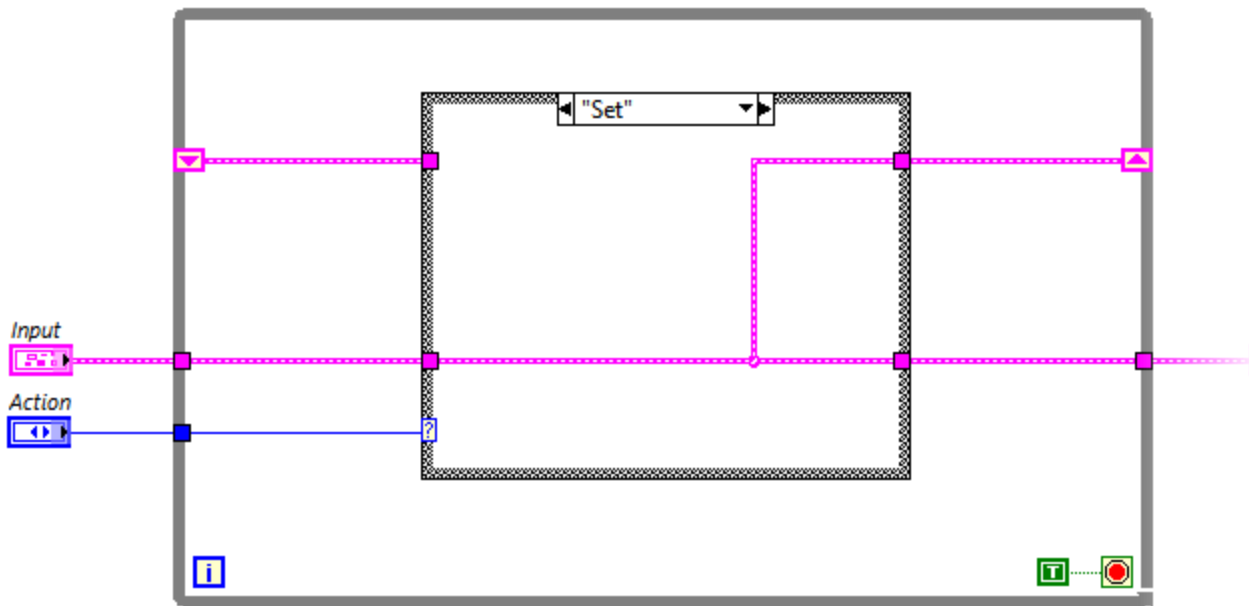
# What is a Functional Global Variable?

- The general form of a functional global variable includes an uninitialized shift register (1) with a single iteration For or While Loop



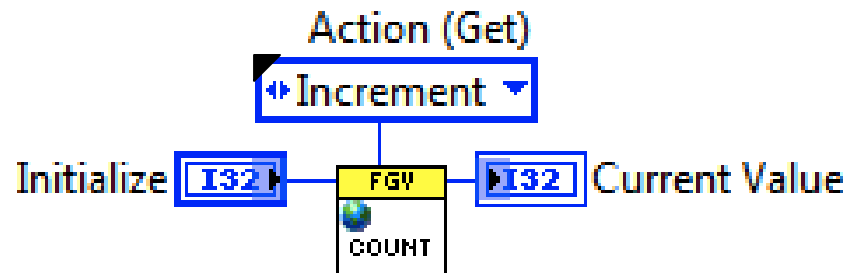
# What is a Functional Global Variable?

- A functional global variable usually has an action input parameter that specifies which task the VI performs
- The uninitialized shift register in a loop holds the result of the operation



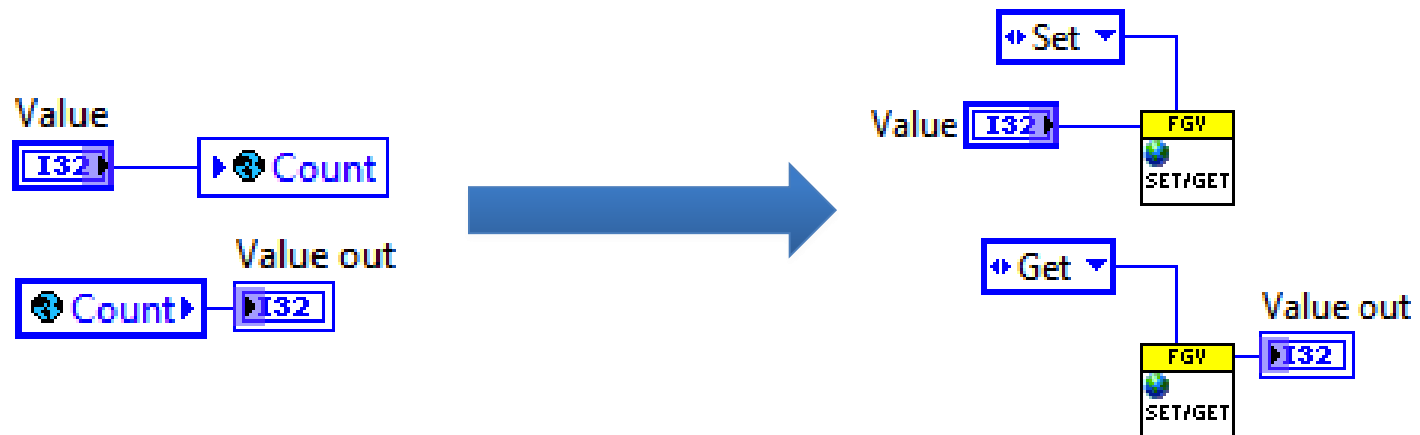
# Best Practices for Documenting FGVs

- The action / method control should be a type defined enum
- Make “Get” the default action / method
  - Include this in the label
- Consider making the action / method required
- Wire to the top connector



# Replacing Global Variables with FGVs

- This is a common initial use case
- Not necessarily a best practice for every application



# Functional Global Variables – Benefits

- Provide *global access to data* while also providing a framework to avoid potential race conditions
- *Encapsulate data* so that debugging and maintenance is easier
- Facilitate the creation of *reusable modules* which simplifies writing and maintenance of code
- Program becomes more *readable*
- *Adorn* data storage

# Comparison of Options

## Functional Global Variables

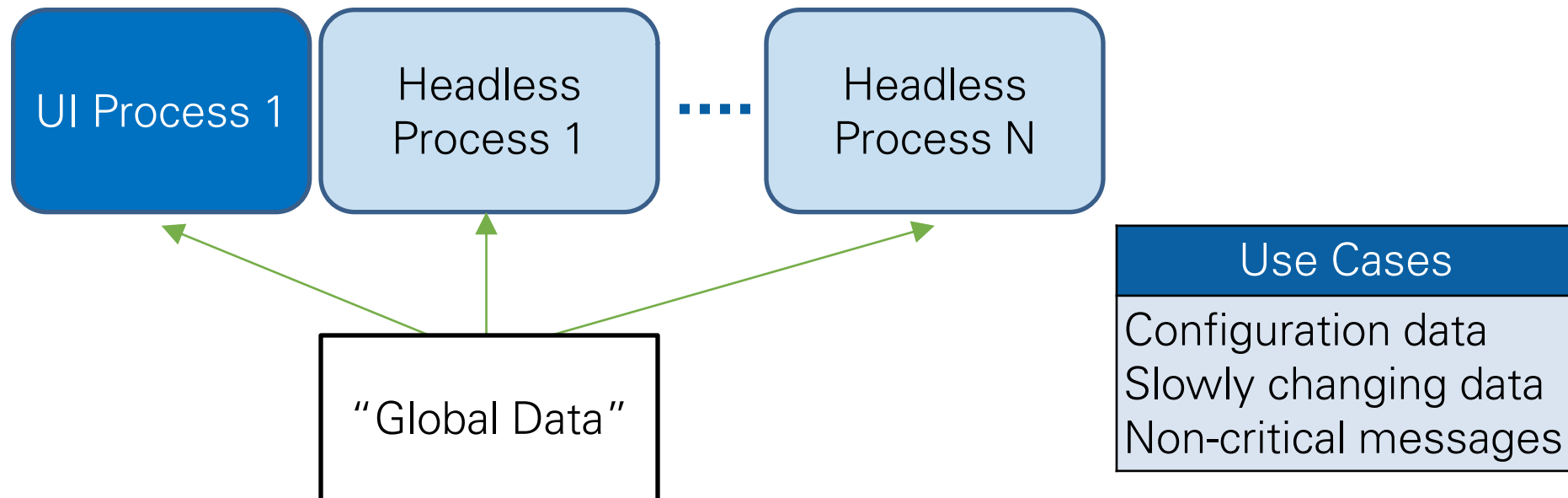
- Can behave like action engines
- Can prevent race conditions
- No copies of data created in memory
- Can handle error wires
- Take time to make

## Global and Local Variables

- Cannot perform actions on data
- Can cause race conditions
- Create copies of data in memory
- Cannot handle error wires
- Drag and drop

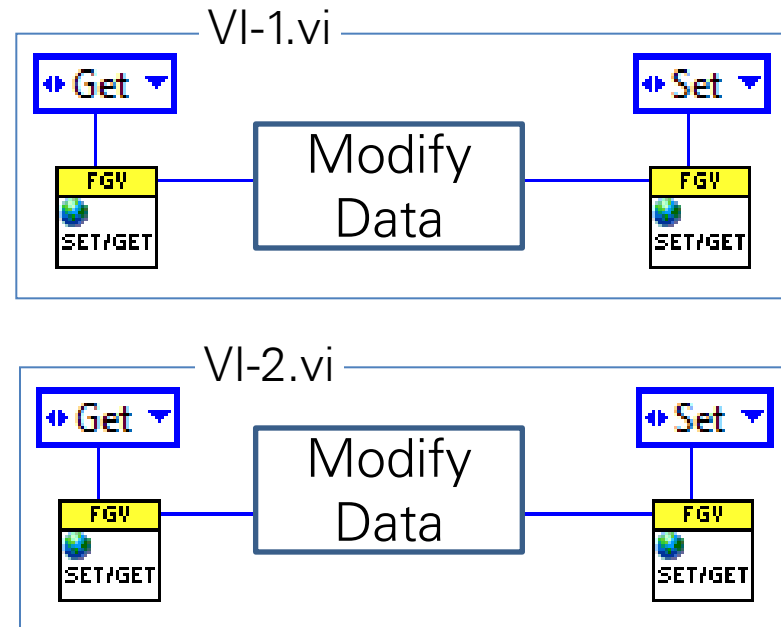
# Considerations for Storing Data

- Data is stored and made “globally” accessible
- Storage mechanism holds only the current value
- Other code modules can access the data as needed
- The potential for race conditions **must be considered**



# Traditional FGVs **Do Not** Eliminate Race Conditions

- What if the FGV includes only set and get methods?



What happens when 2 VIs call the get and both modify the data before either has called the set?

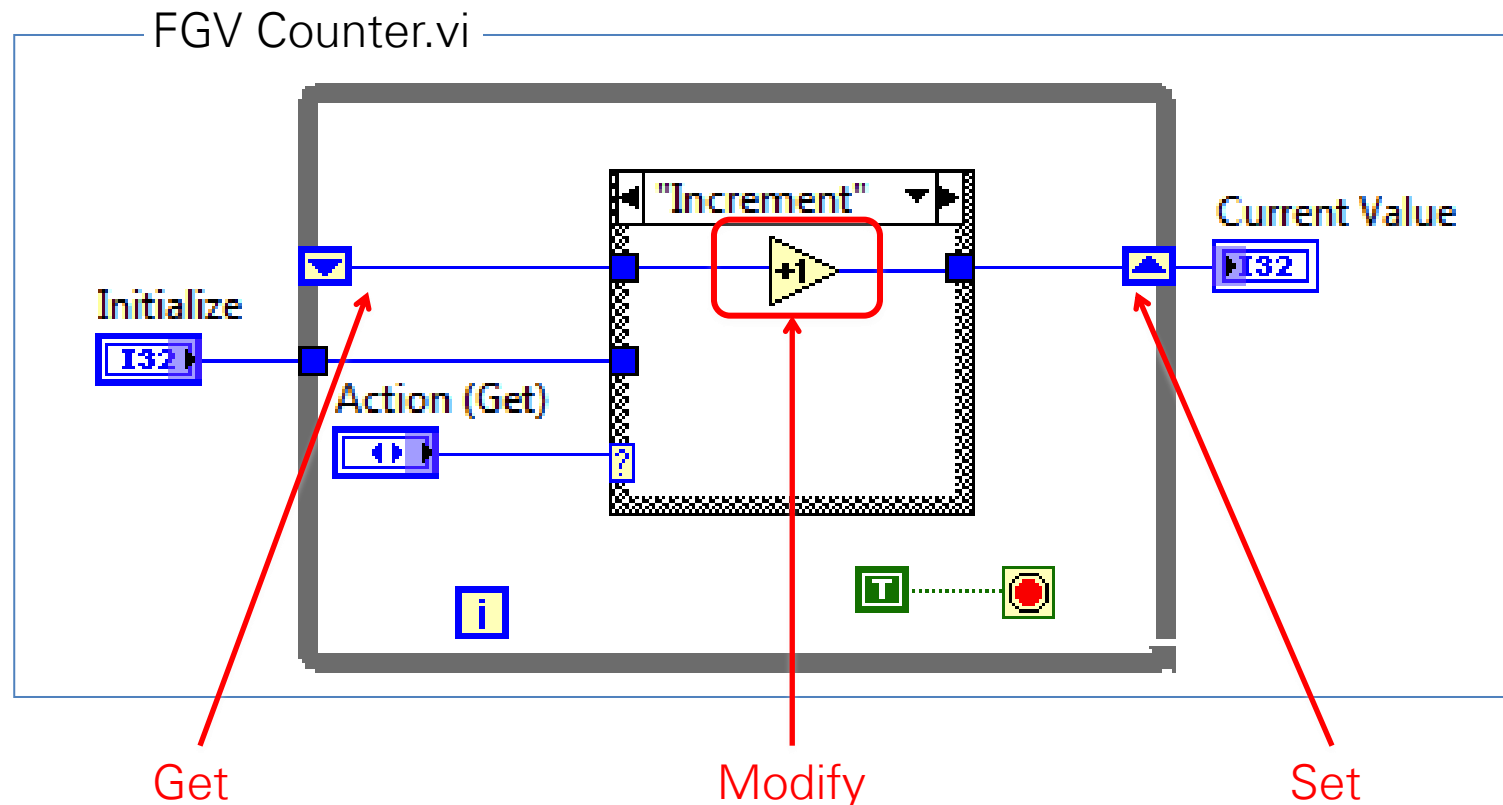
# Use FGVs to Protect Critical Sections of Code

- Identify a critical section of code, such as the modification of a counter value or a timer value
- Identify the actions that modify the data (increment, decrement)
- Encapsulate the entire get/modify/set steps in the FGV

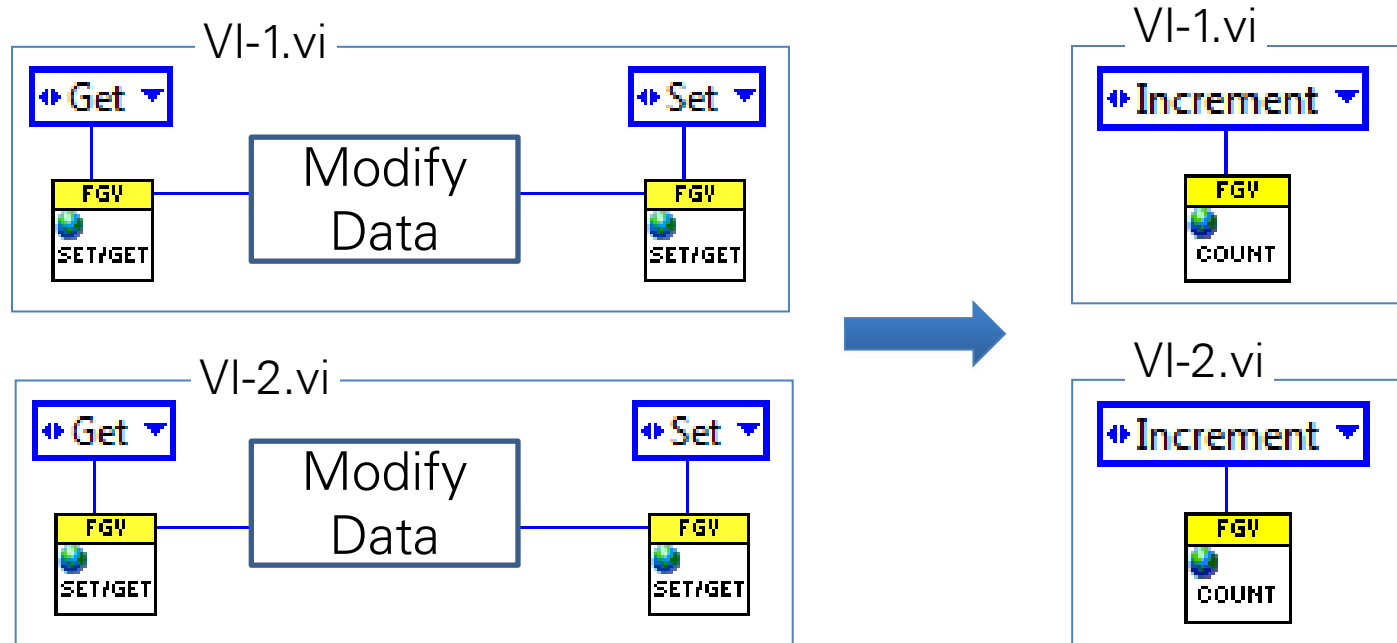
This is commonly called an **Action Engine**.  
It is a special type of FGV.

# FGV – Action Engine Protects Critical Sections of Code

- This action engine wraps the “get/modify/set” around the critical section of code



# Action Engines Protect Critical Sections!

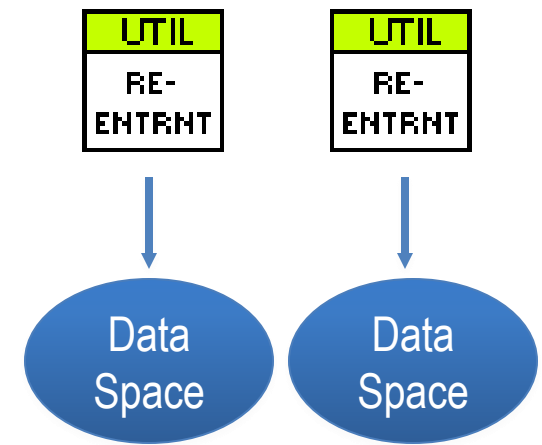
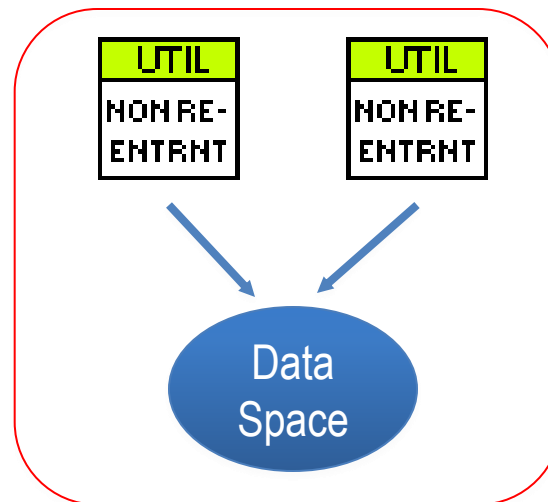


The FGV will block other instance from running until it has completed execution. Therefore, encapsulating the entire action **does prevent** the potential race condition.

# Sidebar: Reentrant vs. Non-Reentrant

- Non-reentrancy is **required** for FGVs
- Reentrancy allows one subVI to be called simultaneously from different places
  - To allow a subVI to be called in parallel
  - To allow a subVI instance to maintain its own state

State (or the data that resides in the uninitialized shift register) is maintained between all instances of the FGV



# Various Inter-process Communication Methods Exist


- FGVs are one tool of many in the toolbox:

	Same target Same application instance	Same target, different application instances / Different targets on network
Storing - Current Value	<ul style="list-style-type: none"><li>• Single-process shared variables</li><li>• Local and global variables</li><li>• FGV, SEQ, DVR</li><li>• CVT</li><li>• Notifiers (Get Notifier)</li></ul>	<ul style="list-style-type: none"><li>• Network-published shared variables (single-element)</li><li>• CCC</li></ul>
Sending Message	<ul style="list-style-type: none"><li>• Queues (N:1)</li><li>• User events (N:N)</li><li>• Notifiers (1:N)</li><li>• User Events</li></ul>	<ul style="list-style-type: none"><li>• TCP, UDP</li><li>• Network Streams (1:1)</li><li>• AMC (N:1)</li><li>• STM (1:1)</li></ul>
Streaming	<ul style="list-style-type: none"><li>• Queues</li></ul>	<ul style="list-style-type: none"><li>• Network Streams</li><li>• TCP</li></ul>

- When you need more than one (counter, timer, etc), investigate Data Value References (DVRs)

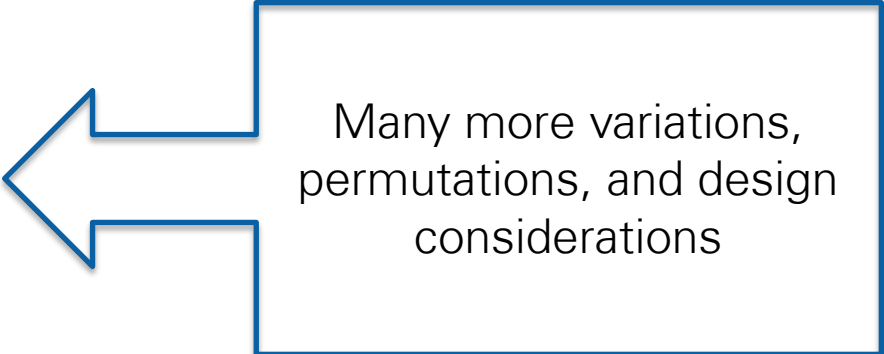
# What Else Do I Need to Know?

- Store Data
- Stream Data



Typically straightforward  
use cases with limited  
implementation options

- Send  
Message



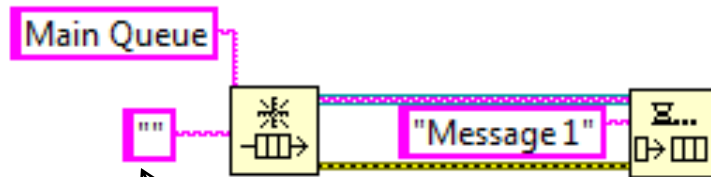
Many more variations,  
permutations, and design  
considerations

## Tactic 2: Queued Message Handlers

- What are Queues?
- What is the Queued Message Handler (QMH)?
  - Basic modifications to the QMH template

# Queues 101: Inter-Process Communication

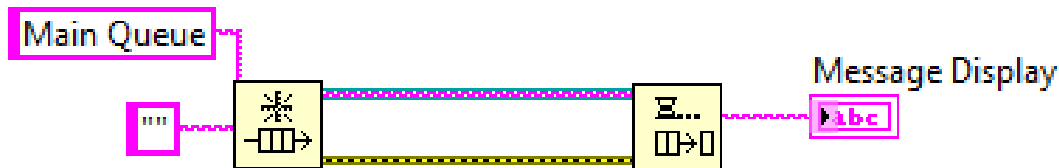
## Adding Elements to the Queue



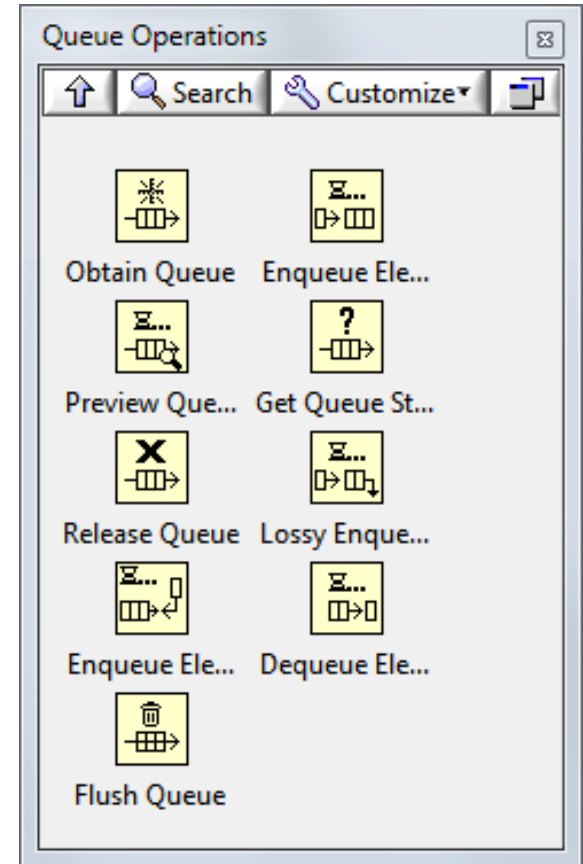
*Select the data type the queue will hold*

*Reference to existing queue in memory*

## Dequeuing Elements



*Dequeue will wait for data or time-out  
(defaults to -1)*



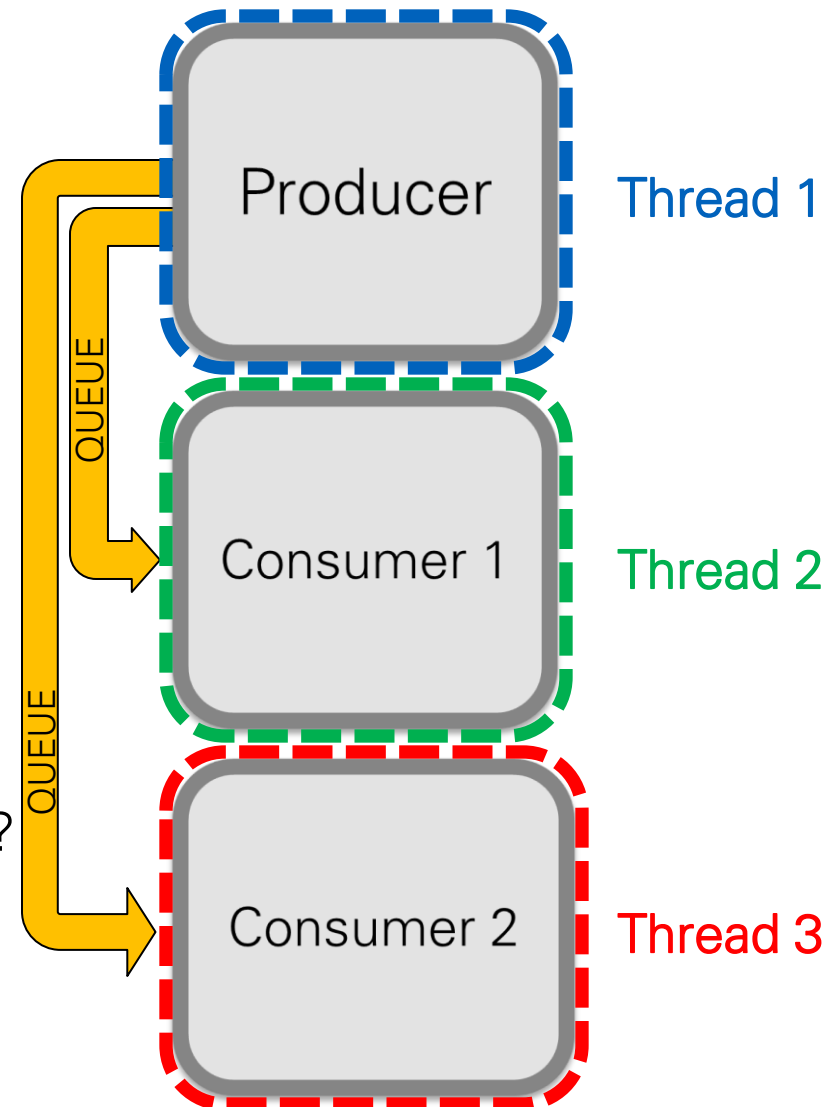
# Producer Consumer Generalization

## Best Practices

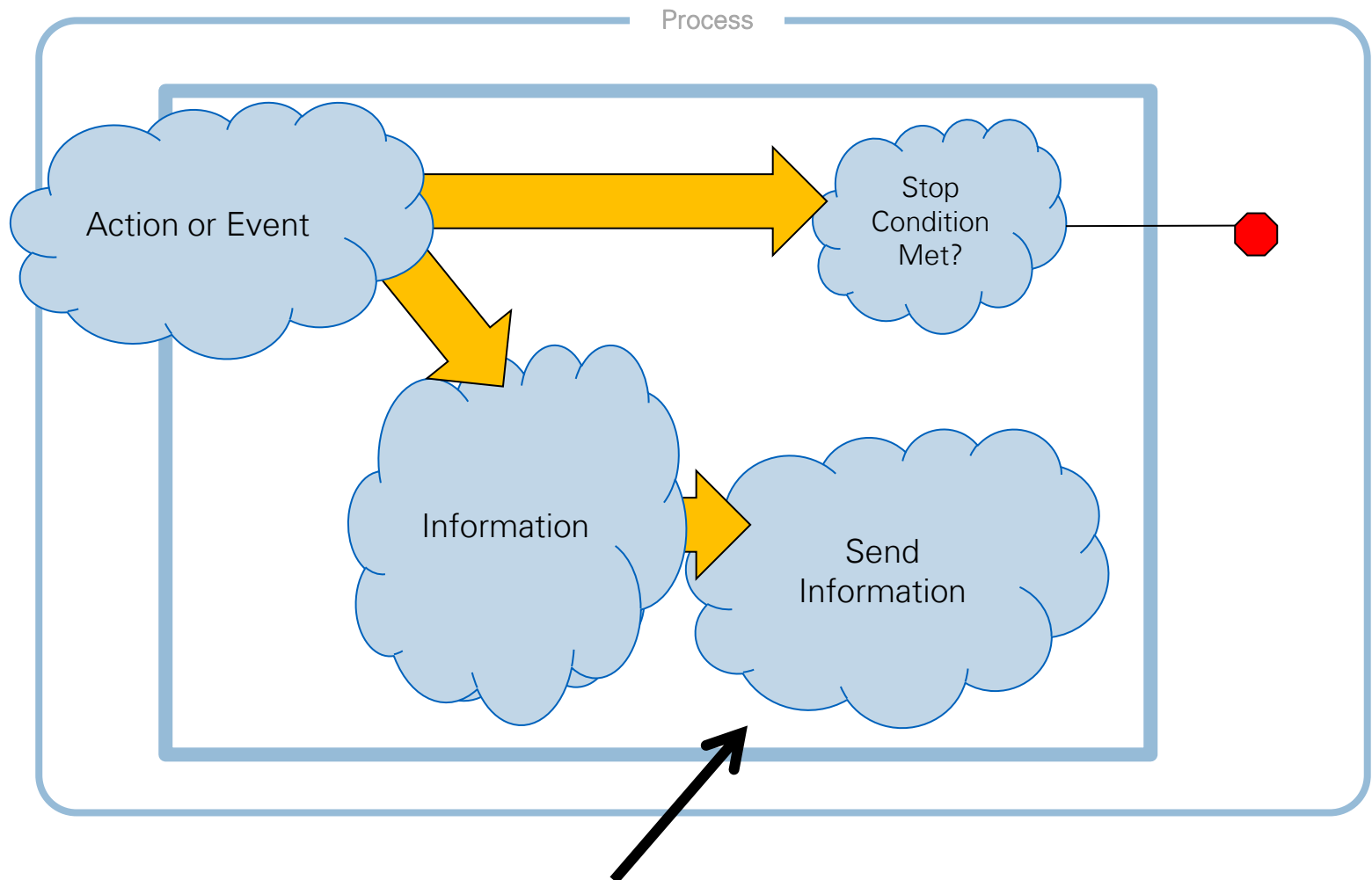
1. One consumer per queue
2. Keep at least one reference to a named queue available at any time
3. Consumers can be their own producers
4. Do not use variables

## Considerations

1. How do you stop all loops?
2. What data should the queue send?

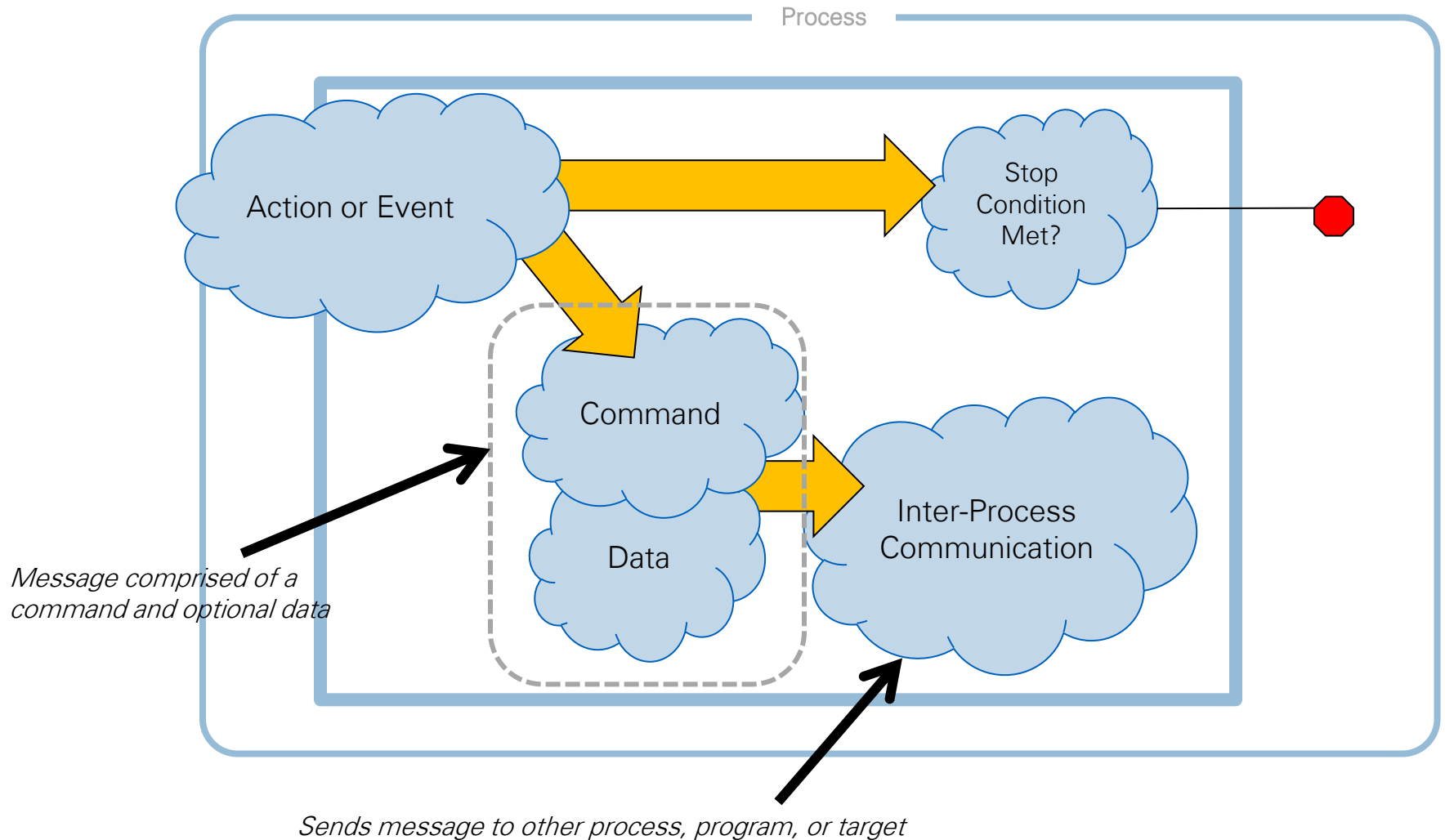


# Anatomy of a "Producer" Process



*Sends message to other process, program, or target*

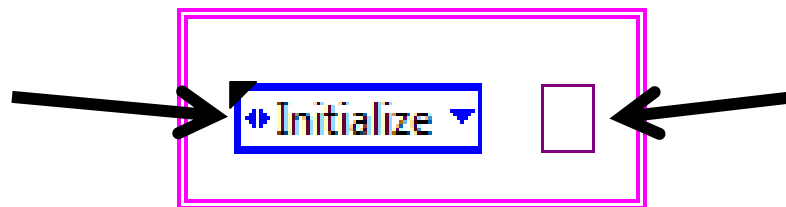
# Anatomy of a Message Producer Process



# Constructing a Message

## *Command*

*Enumerated constants (or strings) list all of the options.*



## *Data*

*Variant allows data-type to vary. Different messages may require different data.*

## Examples:

Command	Data
Initialize UI	Cluster containing configuration data
Populate Menu	Array of strings to display in menu
Resize Display	Array of integers [Width, Height]
Load Subpanel	Reference of VI to Load
Insert Header	String
Stop	-

# Sidebar: Enums versus Strings for Commands?

## Enumerated Constant

- Safer to use – prevents misspellings
- Compiler checks for message validity
- Requires a copy for each API (e.g. “Initialize”)
- “Add case for every value”

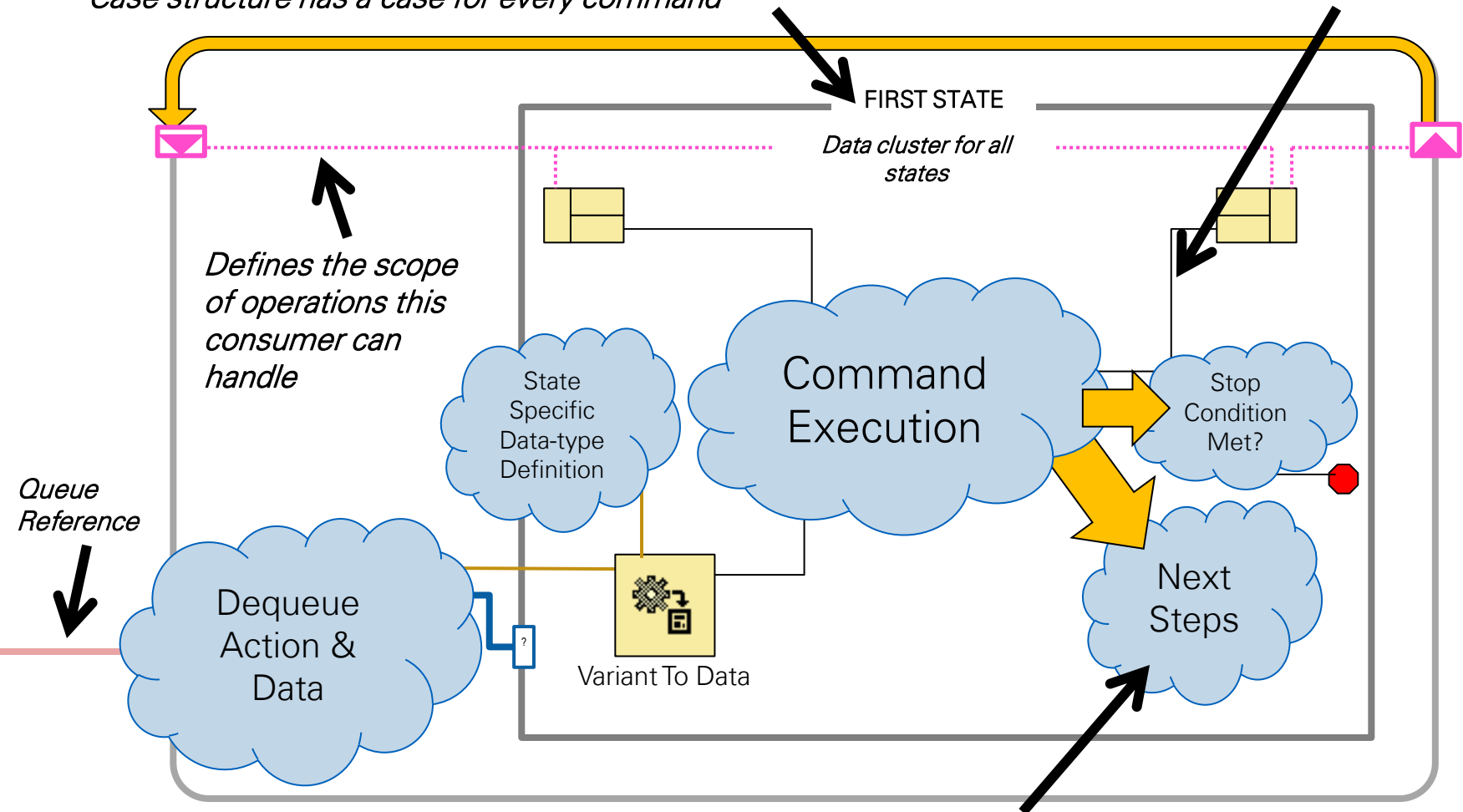
## String

- Misspellings could lead to runtime errors
- Onus is on the developer to get messages correct
- Streamlines usage across multiple APIs
- Universal data type

# Queued Message Handler "Consumer" Process

*Case structure has a case for every command*

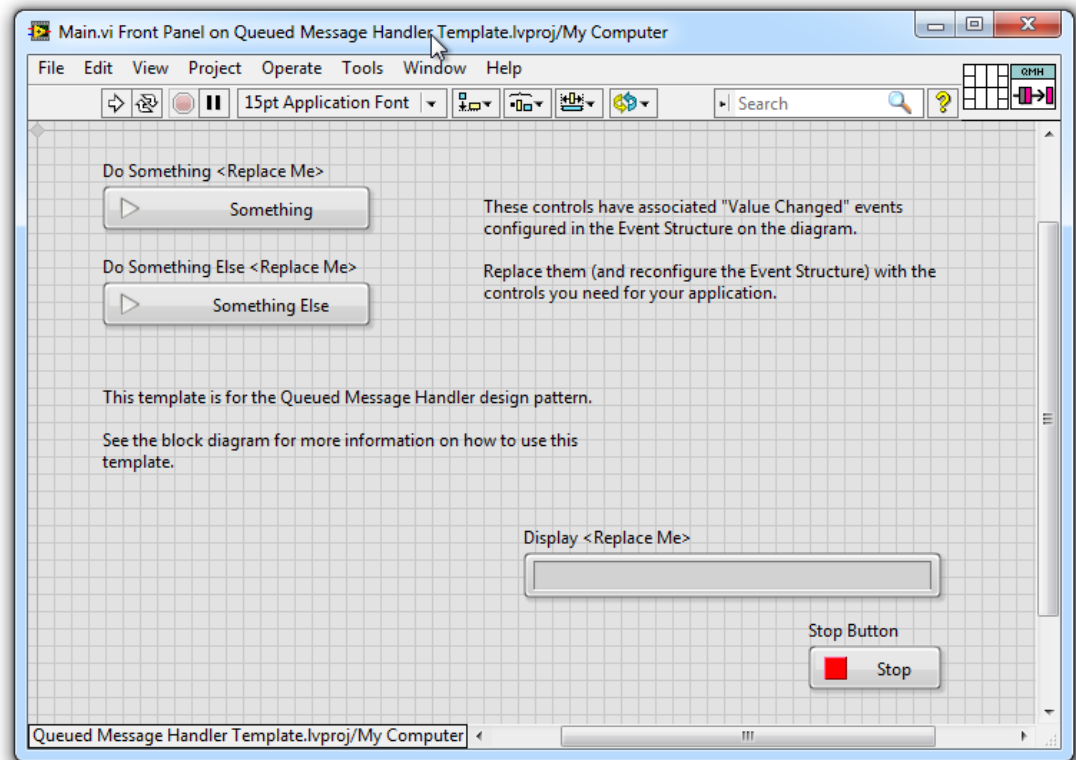
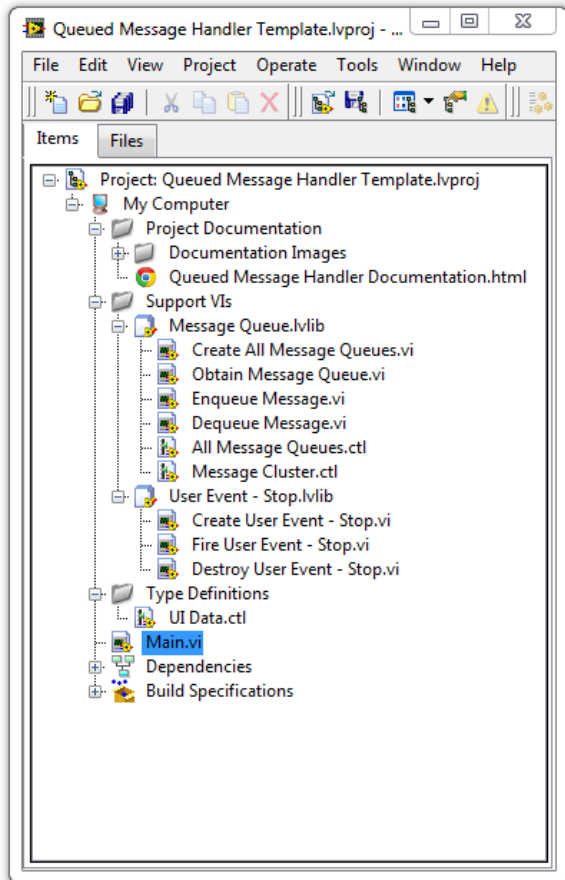
*After command is executed,  
data cluster may be updated*



*Next steps could enqueue new action for any other loop, including this one*

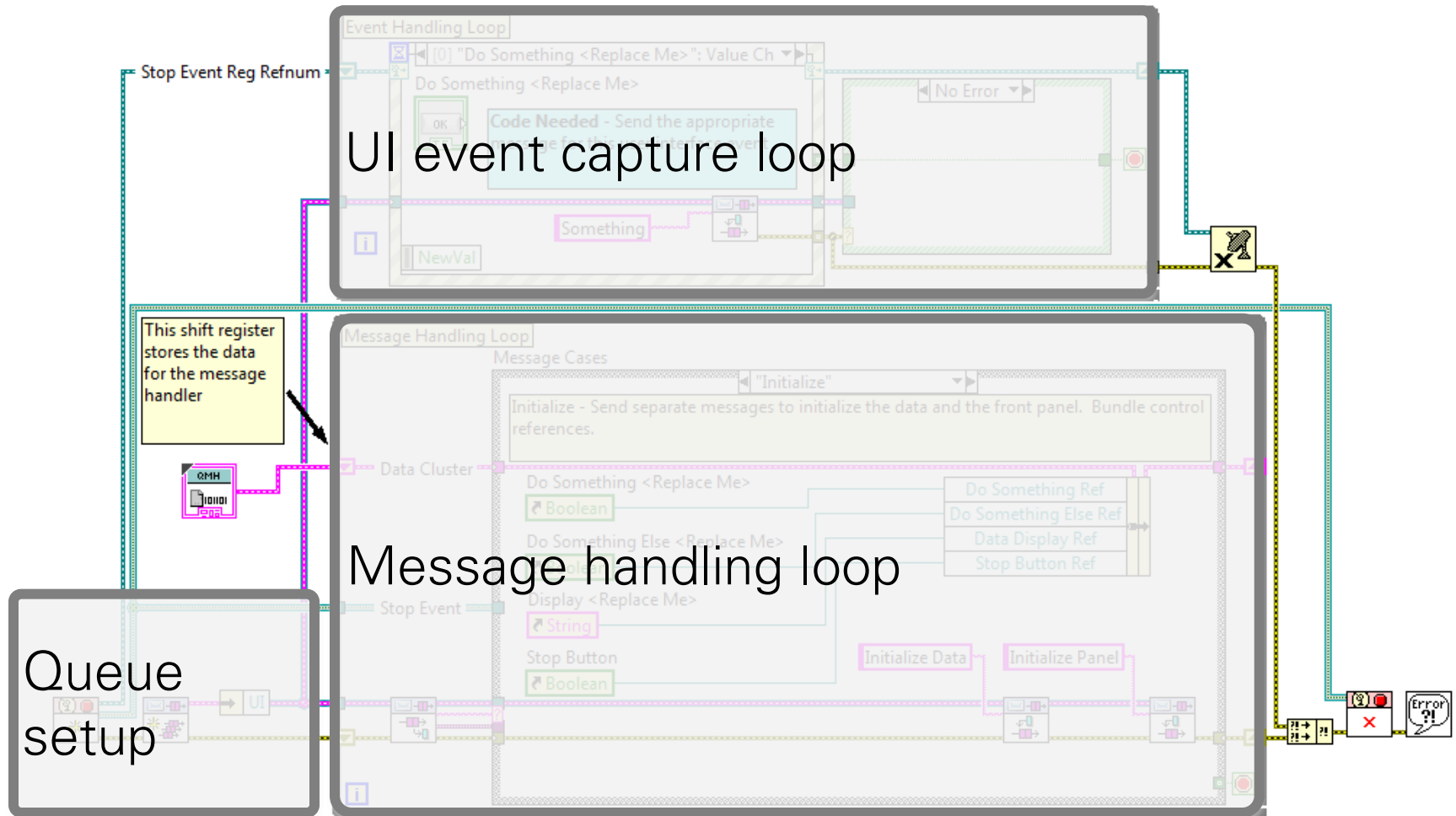
# Queued Message Handler

## Template



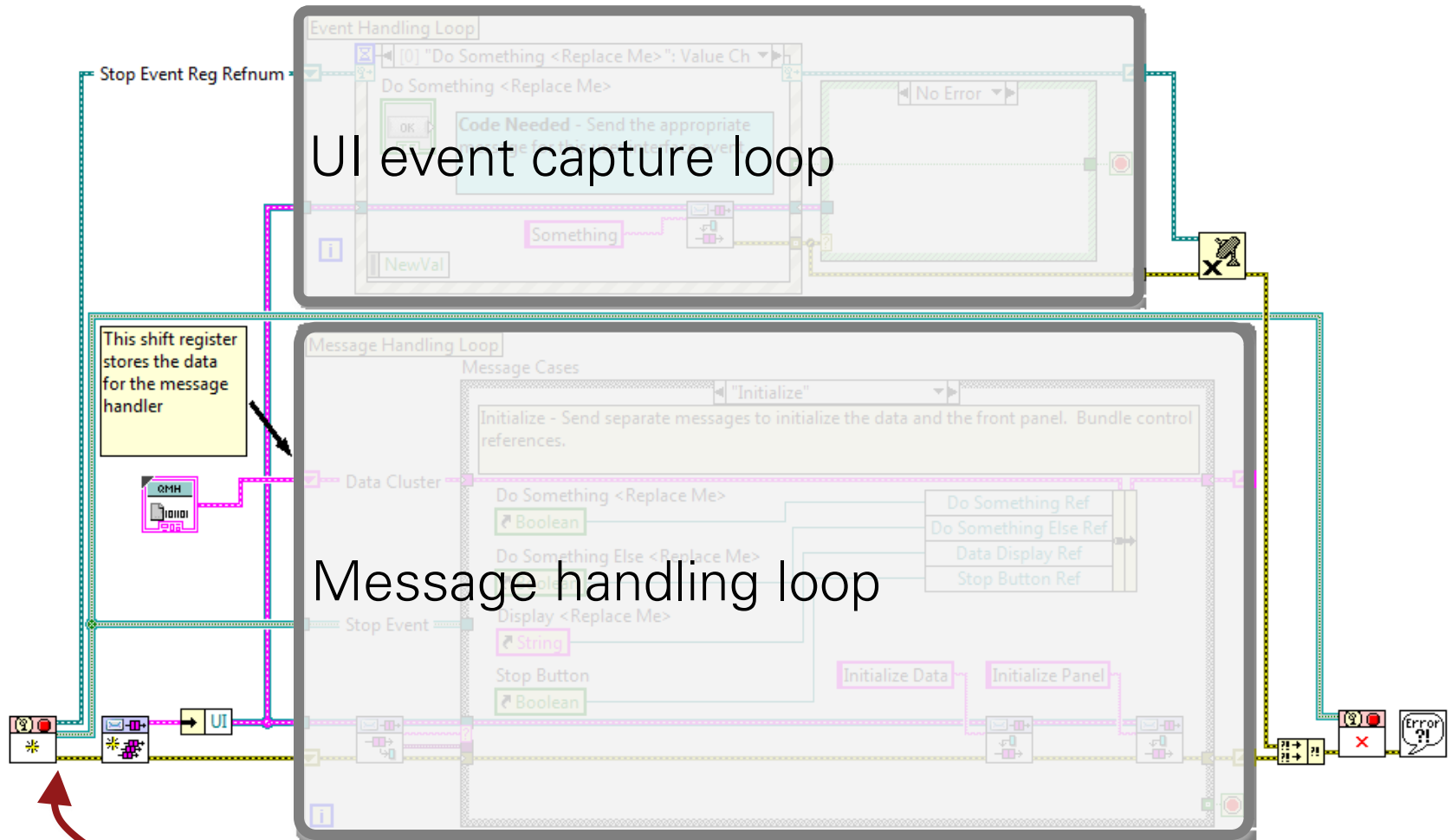
# Queued Message Handler

## Template



# Queued Message Handler

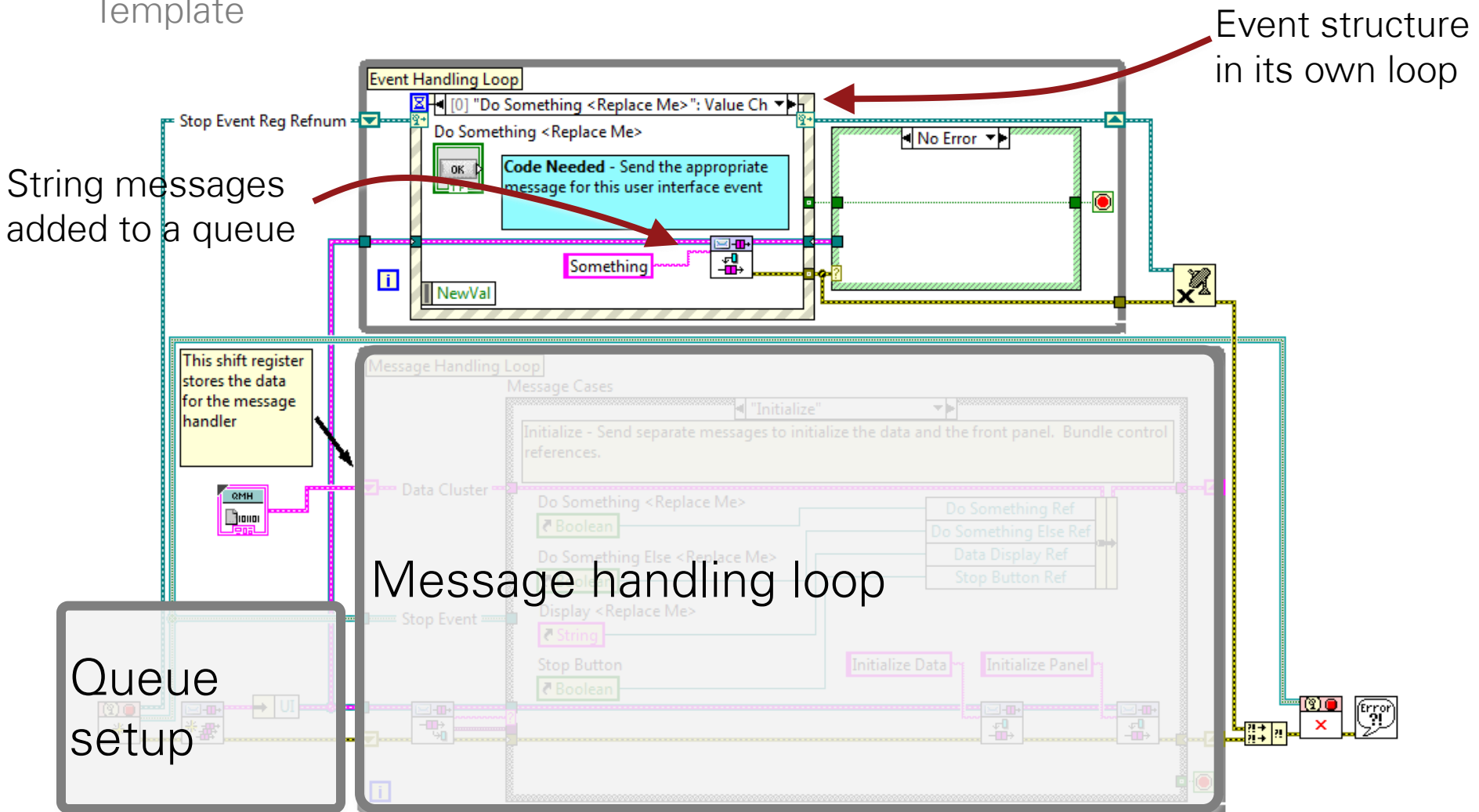
## Template



Create queue for message communication and user event to stop event loop

# Queued Message Handler

Template



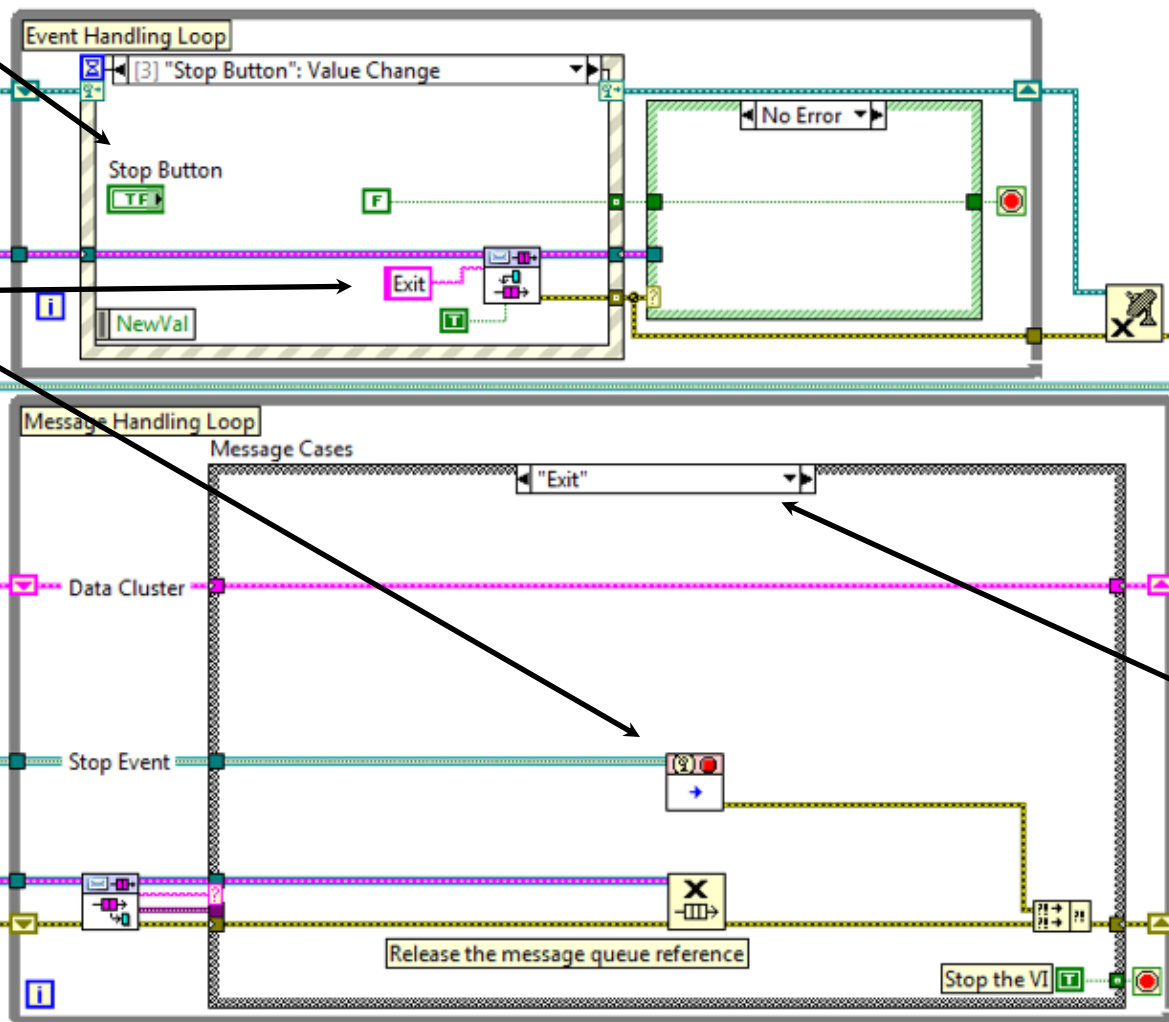
# QMH Extends Producer/Consumer

Basic Controls Included

Exit Strategy

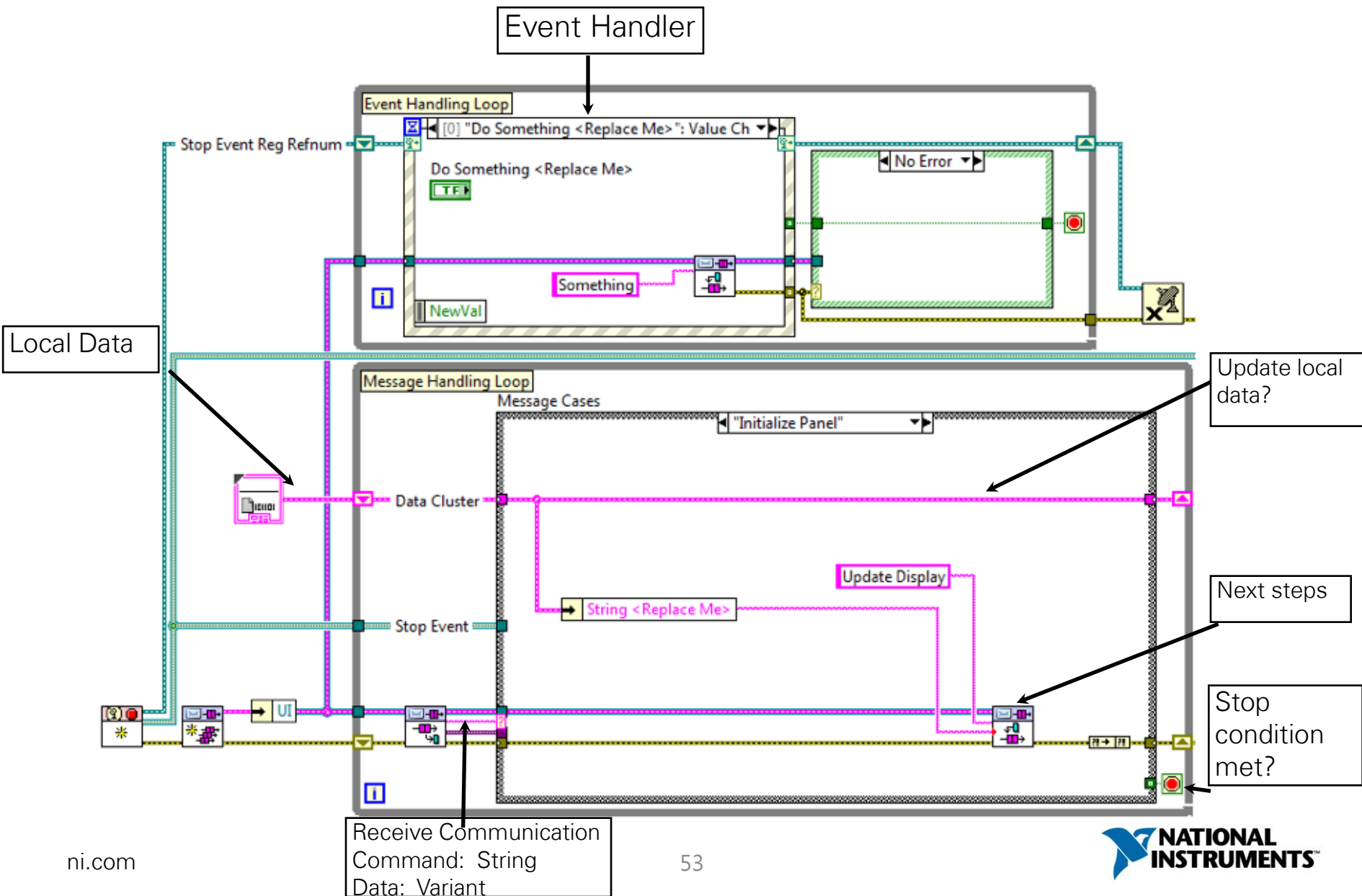
SubVI Encapsulation

ni.com



Standard Cases

# QMH Features



# General Modifications to the QMH Template

- Add Additional Message Handlers
- Add Exit LabVIEW on Run Time to Destroy User Event
  - Exiting when on run-time should exit LabVIEW
- Add Timeout to Dequeue Messages
  - May want to timeout for regular Update Display execution
- Move Register User Event out of Create User Event
  - Forking this wire causes unpredictable results
- Remove Error Case Structure from Producer
  - Adds more real estate and declutters
  - Determine whether a use case exists for keeping this structure
- Determine an Interrupt Strategy
  - What if a process needs to disrupt the flow of tasks?
- ...etc.

# Application-Specific Modifications to the QMH

- Official Login Process
  - Operator login and documentation
- Customized or Interactive Displays
  - Different ways of displaying different types of data
- Standardized Logging
  - Company or application specific file formatting and structure
- Cloud or mobile device publishing
  - Send acquired or analyzed results to a cloud server
- ...etc.

# Summary and Next Steps

- FGVs are an effective data storage mechanism
- Action engines prevent race conditions
- The QMH is really a starting point
  - It will get you really far, but...
  - It is frequently customized
  - It is frequently one component in a larger framework
- Next Steps:
  - Advanced Architectures in LabVIEW CustEd Course
  - History Probe for keeping track of actions:

<https://decibel.ni.com/content/docs/DOC-1106>