## CSE 373: Data Structures and Algorithms

## Hash Tables: Handling Collisions

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## Announcements

- HW3 due Friday Noon
- Office hours for next week have changed. Please see the calendar for the correct info
- We made a mistake in a comment in HW4. We'll push a commit to your repo to correct that. (So expect one more git commit from us.)


## Today

- Review Hashing
- Separate Chaining
- Open addressing with linear probing
- Open addressing with quadratic probing


## Problem (Motivation for hashing)

How can we implement a dictionary such that dictionary operations are efficient?

Idea 1: Create a giant array and use keys as indices.
(This approach is called direct-access table or direct-access map)

Two main problems:

1. Can only work with integer keys?
2. Too much wasted space

Idea 2: What if we
(a) convert any type of key into a non-negative integer key
(b) map the entire key space into a small set of keys (so we can use just the right size array)

## Solution to problem 1: Can only work with integer keys?

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- Everything is stored as bits in memory and can be represented as an integer.
- But the representation can be much simpler (nothing to do with memory).
- For example (just for illustration; this is not how strings, images, and videos are hashed in practice): -Strings can be represented with number of characters in the string, ascii value of the first char, last char - Image can be represented with resolution, size of image, value of the $5^{\text {th }}$ pixel in the image, $100^{\text {th }}$ pixel -Similarly, video can be represented resolution, size, frame rate, size of the $10^{\text {th }}$ frame


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Question: What are some good strategies to pick a hash function? (This is important)

1. Quick: Computing hash should be quick (constant time).
2. Deterministic: Hash value of a key should be the same hash table.
3. Random: A good hash function should distribute the keys uniformly into the slots in the table.

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## Review: The "modulus" (mod) operation

## The "modulus" (mod) operation

The modulus (or mod) operation gives the remainder of a division of one number by another. Written as x mod n or $\mathrm{x} \% \mathrm{n}$.

Examples:

$$
\begin{array}{r}
1 \% 10=1 \\
11 \% 10=1 \\
10 \% 10=0 \\
5746 \% 10=6 \\
71 \% 7=1
\end{array}
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## Common applications of the mod operation:

- finding last digit (\% 10)
- whether a number is odd/even (\% 2)
- wrap around behavior (\% wrap limit)

The application we are interested in is the wrap around behavior.
It lets us map any large integer into an index in our array of size m (using \% m)

## Implementing a simple hash table (assume no collisions)

```
public V get(int key) {
    return this.array[key].value;
}
public void put(int key, V value) {
    this.array[key] = value;
}
public void remove(int key) {
    this.array[key] = null;
}
```


## Implementing a simple hash table (assume no collisions)

```
public V get(int key) {
    key = getHash(key)
    return this.array[key].value;
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}
public void remove(int key) {
    key = getHash(key)
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}
```

```
public int getHash(int a) {
    return a % this.array.length;
}
```


## Our simple hash table: insert (1000)



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## Hash collision

What is a hash collision?
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Why is this a problem?

- We put keys in slots determined by the hash function. That is, we put k1 at index h(k1),
- A collision means the natural choice slot is taken
- We cannot replace k1 with k2 (because the keys are different)
- So the problem is where do we put k2?

Strategies to handle hash collision

## Strategies to handle hash collision

There are multiple strategies. In this class, we'll cover the following three:

1. Separate chaining
2. Open addressing

- Linear probing
- Quadratic probing

3. Double hashing

## Separate chaining

- Separate chaining is a collision resolution strategy where collisions are resolved by storing all colliding keys in the same slot (using linked list or some other data structure)
- Each slot stores a pointer to another data structure (usually a linked list or an AVL tree)
indices

```
put(21, value21)
put(44, value44)
```



Note: For simplicity, the table shows only keys, but in each slot/node both, key and value, are stored.

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## Separate chaining: Running Times

What are the running times for:

```
insert
    Best:
    Worst:
find
    Best:
    Worst:
delete
    Best:
    Worst:
```


## Separate chaining: Running Times

What are the running times for:
insert
Best: $O(1)$
Worst: $O(n)$ (if insertions are always at the end of the linked list)
find
Best: $O(1)$
Worst: $O(n)$

```
delete
    Best: O(1)
    Worst: O(n)
```


## Load Factor

## Load Factor ( $\lambda$ )

Ratio of number of entries in the table to table size.
If $n$ is the total number of (key, value) pairs stored in the table and c is capacity of the table (i.e., array),
$\frac{n}{c}$

## Worksheet Q1-Q3

Q1) The following table shows the resulting hash table after inserting keys $1,16,8$, and 5 . The hash table uses the hash function $\mathrm{h}(\mathrm{x})=\mathrm{x} \% 7$ and separate chaining to avoid collisions. Now suppose we insert keys 7 and 9 in this hash table. What would the resulting hash table look like (show where the values would be inserted).


## Worksheet Q3

(Q3) What is the load factor of the following hash table?


## Open Addressing

- Open addressing is a collision resolution strategy where collisions are resolved by storing the colliding key in a different location when the natural choice is full.


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```
```

put(21, value21)

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indices


Note: For simplicity, the table shows only keys, but in each slot both, key and value, are stored.

## Open Addressing: Linear probing

- Open addressing is a collision resolution strategy where collisions are resolved by storing the colliding key in a different location when the natural choice is full.


## indices

```
put(21, value21)
```


## Linear probing

```
Index = hash(k) + 0 (if occupied, try next i)
    = hash(k) + 1 (if occupied, try next i)
    = hash(k) + 2 (if occupied, try next i)
    = ..
    = ..
    = ..
```

        Note: For simplicity, the table shows only keys, but
        in each slot both, key and value, are stored.
    
## Open Addressing: Quadratic probing

- Open addressing is a collision resolution strategy where collisions are resolved by storing the colliding key in a different location when the natural choice is full.


## indices

```
put(21, value21)
```


## Quadratic probing

$$
\begin{array}{rlrl}
\text { Index } & =\text { hash }(k)+0 & & \text { (if occupied, try next } \left.i^{\wedge} 2\right) \\
& =\text { hash }(k)+1^{\wedge} 2 & & \text { (if occupied, try next } \left.\mathrm{i}^{\wedge} 2\right) \\
& =\text { hash }(k)+2^{\wedge} 2 & & \text { (if occupied, try next } \left.i^{\wedge} 2\right) \\
& =\text { hash }(k)+3^{\wedge} 2 & & \text { (if occupied, try next } \left.i^{\wedge} 2\right) \\
& =. . & \\
& =. & &
\end{array}
$$

[^0]
## Worksheet Q4

(Q4) Each table uses the hash function $h(x)=x \% 7$, but different collision handling strategies. Show where key 8 will be inserted in the following hash tables.
(4a) The following hash tables uses separate chaining

(4b) The following hash tables uses open addressing with linear probing

| 0 | 1 | 2 | 3 | 4 | 5 | 6 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 7 | 1 | 16 |  |  |  |  |

(4c) The following hash tables uses open addressing with quadratic probing.

| 0 | 1 | 2 | 3 | 4 |  | 5 |  | 6 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: |
| 7 | 1 | 16 |  |  |  |  |  |  |

## Worksheet Q5

(Q5) What is the worst case tight-O for the following operations:
(5a) Insert in a separate chaining hash table:
(5b) Insert in an open addressing hash table that uses linear probing to resolve collisions:
(5c) Find in a separate chaining hash table:
(5d) Find in an open addressing hash table that uses linear probing to resolve collisions:


[^0]:    Note: For simplicity, the table shows only keys, but in each slot both, key and value, are stored.

